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A 4/3 Approximation for 2-Vertex-Connectivity

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ABSTRACT. The 2-Vertex-Connected Spanning Subgraph problem (2VCSS) is among the most basic NP-hard (Survivable) Network Design problems: we are given an (unweighted) undirected graph *G*. Our goal is to find a spanning subgraph *S* of *G* with the minimum number of edges which is 2-vertex-connected, namely *S* remains connected after the deletion of an arbitrary node. 2VCSS is well-studied in terms of approximation algorithms, and the current best (polynomial-time) approximation factor is 10/7 by Heeger and Vygen [SIDMA'17] (improving on earlier results by Khuller and Vishkin [STOC'92] and Garg, Vempala and Singla [SODA'93]).

Here we present an improved 4/3 approximation. Our main technical ingredient is an approximation preserving reduction to a conveniently structured subset of instances which are "almost" 3-vertex-connected. The latter reduction might be helpful in future work.

1. Introduction

Real-world networks are prone to failures. For this reason it is important to design them so that they are still able to support a given amount of traffic despite a few (typically temporary) failures of nodes or edges. The basic goal of survivable network design is to construct cheap networks which are resilient to such failures.

Most natural survivable network design problems are NP-hard, and a lot of work was dedicated to the design of approximation algorithms for them. One of the most basic survivable network design problems is the 2-Vertex-Connected Spanning Subgraph problem (2VCSS). Recall that an (undirected) graph G = (V, E) is k-vertex-connected (kVC) if, after removing any subset

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W of at most k - 1 nodes (with all the edges incident to them), the residual graph $G[V \setminus W]$ is connected. In particular, in a 2VC graph *G* we can remove any single node while maintaining the connectivity of the remaining nodes (intuitively, we can tolerate a single node failure). In 2VCSS we are given a 2VC (unweighted) undirected graph G = (V, E), and our goal is to compute a minimum cardinality subset $S \subseteq E$ of edges such that the (spanning) subgraph (V, S) is 2VC.

2VCSS is NP-hard: indeed an *n*-node graph *G* admits a Hamiltonian cycle iff it contains a 2VC spanning subgraph with *n* edges. Czumaj and Lingas [13] proved that the problem is APX-hard, hence it does not have a PTAS unless P=NP. A 2-approximation for 2VCSS can be obtained in different ways. For example one can compute an (open) ear decomposition of the input graph and remove the trivial ears (containing a single edge). The resulting graph is 2VC and contains at most 2(n - 1) edges (while the optimum solution must contain at least *n* edges). The first non-trivial 5/3 approximation was obtained by Khuller and Vishkin [27]. This was improved to 3/2 by Garg, Vempala and Singla [20] (see also an alternative 3/2 approximation by Cheriyan and Thurimella [11]). Finally Heeger and Vygen [24] presented the current-best 10/7 approximation¹. Our main result is as follows (please see Section 2 for an overview of our approach):

THEOREM 1.1. There is a polynomial-time $\frac{4}{3}$ -approximation algorithm for 2VCSS.

1.1 Related Work

An undirected graph *G* is *k*-edge-connected (kEC) if it remains connected after removing up to k - 1 edges. The 2-Edge-Connected Spanning Subgraph problem (2ECSS) is the natural edge-connectivity variant of 2VCSS, where the goal is to compute a 2EC spanning subgraph with the minimum number of edges. Like 2VCSS, 2ECSS does not admit a PTAS unless P = NP [13]. It is not hard to compute a 2 approximation for 2ECSS. For example it is sufficient to compute a DFS tree and augment it greedily. Khuller and Vishkin [28] found the first non-trivial 3/2-approximation algorithm. Cheriyan, Sebö and Szigeti [10] improved the approximation factor to 17/12. This was further improved to 4/3 in two independent and drastically different works by Hunkenschröder, Vempala and Vetta [25] and Sebö and Vygen [34]. The current best and very recent $\frac{118}{89} + \varepsilon < 1.326$ approximation is due to Garg, Grandoni and Jabal Ameli [19]. Our work exploits several ideas from the latter paper. The *k*-Edge Connected Spanning Subgraph problem (kECSS) is the natural generalization of 2ECSS to any connectivity $k \ge 2$ (see, e.g., [11, 17]).

A major open problem in the area is to find a better than 2 approximation for the weighted version of 2ECSS. This is known for the special case with 0-1 edge weights, a.k.a. the Forest

¹ Before [24] a few other papers claimed even better approximation ratios [23, 26], however they have been shown to be buggy or incomplete, see the discussion in [24].

Augmentation problem, by the recent work by Grandoni, Jabal-Ameli and Traub [21] (see also [2, 6, 7] for the related Matching Augmentation problem).

A problem related to kECSS is the *k*-Connectivity Augmentation problem (kCAP): given a *k*-edge-connected undirected graph *G* and a collection of extra edges *L* (*links*), find a minimum cardinality subset of links *L'* whose addition to *G* makes it (*k*+1)-edge-connected. It is known [14] that kCAP can be reduced to the case k = 1, a.k.a. the Tree Augmentation problem (TAP), for odd *k* and to the case k = 2, a.k.a. the Cactus Augmentation problem (CacAP), for even *k*. Several approximation algorithms better than 2 are known for TAP [1, 8, 9, 15, 16, 22, 30, 29, 31], culminating with the current best 1.393 approximation by Cecchetto, Traub and Zenklusen [5]. Until recently no better than 2 approximation was known for CacAP (excluding the special case where the cactus is a single cycle [18]): the first such algorithm was described by Byrka, Grandoni and Jabal Ameli [4], and later improved to 1.393 in [5]. In a recent breakthrough by Traub and Zenklusen, a better than 2 (namely 1.694) aproximation for the weighted version of TAP was achieved [36] (later improved to $1.5 + \varepsilon$ in [35]). Partial results in this direction where achieved earlier in [1, 12, 16, 22, 32]. Even more recently, Traub and Zenklusen obtained a $1.5 + \varepsilon$ approximation for the weighted version of kCAP [35].

1.2 Preliminaries

We use standard graph notation. For a graph G = (V, E), we let V(G) = V and E(G) = E denote its nodes and edges, respectively. For $W \subseteq V$ and $F \subseteq E$, we use the shortcuts $G \setminus F := (V, E \setminus F)$ and $G \setminus W := G[V \setminus W]$. Throughout this paper we sometimes use interchangeably a subset Fof edges and the corresponding subgraph (W, F), $W = \{v \in V : v \in f \in F\}$. The meaning will be clear from the context. For example, we might say that $F \subseteq E$ is 2VC or that F contains a connected component. In particular, we might say that $S \subseteq E$ is a 2VC spanning subgraph. Also, given two subgraphs G_1 and G_2 , by $G' = G_1 \cup G_2$ we mean that G' is the subgraph induced by $E(G_1) \cup E(G_2)$. We sometimes represent paths and cycles as sequence of nodes. A k-vertex-cut of G is a subset W of k nodes such that $G[V \setminus W]$ has at least 2 connected components. A node defining a 1-vertex-cut is a cut vertex. By $OPT(G) \subseteq E(G)$ we denote an optimum solution to a 2VCSS instance G, and let opt(G) := |OPT(G)| be its size. All the algorithms described in this paper are deterministic.

We will use the notion of block-cutpoint graph. The block-cutpoint graph G^* of a graph G is a bipartite graph that has a node corresponding to every maximal 2VC subgraph of G, as well as a node corresponding to every cut vertex of G. Furthermore, G^* has an edge ub iff u is a cut vertex and $u \in V(B)$, where B is the maximal 2VC subgraph of G corresponding to b in G. It is a well-known fact [37, Chapter 3] that the block-cutpoint graph of a graph G is a tree if G is connected.

2. Overview of Our Approach

In this section we sketch the proof of our 4/3-approximation (Theorem 1.1). The details and proofs which are omitted here will be given in the following technical sections.

Our result relies on 3 main ingredients. The first one is an approximation-preserving (up to a small additive term) reduction of 2VCSS to instances of the same problem on properly *structured* graphs, which are "almost" 3VC in a sense described later (see Section 2.1).

At this point we compute a minimum-size 2-edge-cover *H* similarly to prior work: this provides a lower bound on the size of the optimal solution. For technical reasons, we transform *H* into a *canonical* form, without increasing its size (see Section 2.2).

The final step is to convert *H* into a feasible solution *S*. Starting from S = H, this is done by iteratively adding edges to and removing edges from *S* in a careful manner. In order to keep the size of *S* under control, we assign 1/3 credits to each edge of the initial *S*, and use these credits to pay for any increase in the number of edges of *S* (see Section 2.3). We next describe the above ingredients in more detail.

2.1 A Reduction to Structured Graphs

Our first step is an approximation-preserving (up to a small additive factor) reduction of 2VCSS to instances of the same problem on properly *structured* graphs. This is similar in spirit to an analogous reduction for 2ECSS in [19]. In particular, we exploit the notion of irrelevant edges and isolating cuts defined in that paper. We believe that our reduction might be helpful also in future work.

In more detail, we can get rid of the following *irrelevant* edges.

DEFINITION 2.1 (Irrelevant edge). Given a graph *G*, we say that an edge $e = uv \in E(G)$ is *irrelevant* if $\{u, v\}$ is a 2-vertex-cut of *G*.

LEMMA 2.2. Given a 2VC graph G, let e be an irrelevant edge of G. Then, every optimal 2VCSS solution for G does not contain e.

PROOF. Recall that an ear-decomposition of an undirected graph *G* is a sequence of paths or cycles P_1, \ldots, P_k (ears) spanning E(G) such that P_1 is a cycle and P_i , i > 1, has its internal nodes disjoint from $V_{i-1} := V(P_1) \cup \ldots \cup V(P_{i-1})$ and its endpoints (or one node if P_i is a cycle) in V_{i-1} . We say that an ear-decomposition is open if P_i is a path, for i > 1. Every 2VC graph admits an open ear decomposition [33, Chapter 15]. We will need the following observation:

FACT 2.3. Suppose that a minimal solution *S* to 2VCSS on a graph *G* contains a cycle *C*. Then *S* does not contain any chord *f* of *C*. Indeed, otherwise consider any open ear decomposition of *S* which uses *C* as a first ear. Then *f* would be a trivial ear (consisting of a single edge) of the decomposition, and thus $S \setminus \{f\}$ would also be 2VC, contradicting the minimality of *S*.

Let $H \subseteq E$ be any optimal (hence minimal) solution to 2VCSS on *G*. Assume by contradiction that *H* contains an irrelevant edge e = uv. Removing *u* and *v* splits *H* into distinct connected components C_1, \ldots, C_k , with $k \ge 2$. Each one of those components has edges $u_i u$, $v_i v$ in *H*, where $u_i, v_i \in C_i$ for $i \in \{1, \ldots, k\}$, otherwise *H* would contain a cut vertex. Let P_1 be a path from u_1 to v_1 in C_1 , and P_2 be a path from v_2 to u_2 in C_2 . Then *e* is a chord of the cycle $P_1 \cup P_2 \cup \{uu_1, v_1v, vv_2, u_2u\}$, contradicting the minimality of *H* by Fact 2.3.

We can enforce (see later) that our graph *G* is "almost" 3VC, in the sense that the only 2-vertexcuts of *G* are a very specific type of *isolating* cuts defined as follows.

DEFINITION 2.4 (Isolating cut). Given a 2-vertex-cut $\{u, v\}$ of a graph *G*, we say that this cut is *isolating* if $G \setminus \{u, v\}$ has exactly two connected components, one of which consists of 1 node. Otherwise the cut is *non-isolating*.

Assuming that there are no non-isolating cuts, we can avoid the following local configuration: this will be helpful in the rest of our analysis.

DEFINITION 2.5 (Removable 5-cycle). We say that a 5-cycle *C* of a 2VC graph *G* is *removable* if it has at least two vertices of degree 2 in *G*.

LEMMA 2.6. Given a 2VC graph G without non-isolating cuts and with at least 6 nodes. Let C be a removable 5-cycle of G. Then in polynomial time one can find an edge e of C such that there exists an optimum solution to 2VCSS on G not containing e (we say that e is a removable edge).

PROOF. Assume $C = v_1 v_2 v_3 v_4 v_5$. If *C* has two vertices of degree 2 that are adjacent in *C*, namely v_1 and v_2 , then $\{v_3, v_5\}$ is a non-isolating cut of *G*, a contradiction. Thus, we can assume that *C* has exactly two non-adjacent vertices of degree 2, say v_1 and v_3 w.l.o.g.

We will show that the edge $e = v_4v_5$ is the desired removable edge. Let H be an optimal 2VCSS solution for G that uses the edge v_4v_5 . Observe that in this case since v_1 and v_3 have degree 2, then H must contain all the edges of C.

To complete the argument we show that there exists an edge $f \in E(G) \setminus E(H)$ such that v_4v_5 is a chord of a cycle in $H' := H \cup \{f\}$: hence we can remove v_4v_5 from H' using Fact 2.3 to obtain an alternative optimum solution not containing v_4v_5 .

Let $H'' = H \setminus \{v_4v_5\}$. There is no cycle C' in H'' that contains both v_4 and v_5 , otherwise v_4v_5 is a chord of C' in H, contradicting the minimality of H by Fact 2.3. Therefore if we remove v_2 from H'', there must be no paths from v_4 to v_5 . This means that there is a partition of $V(G) \setminus \{v_2\}$ into non-empty sets V_1 and V_2 such that, $\{v_3, v_4\} \in V_1$, $\{v_1, v_5\} \in V_2$ and there is no edge in H'' between V_1 and V_2 . Since $|V(G)| \ge 6$, then we can assume w.l.o.g that $|V_1| \ge 3$.

There must be an edge $f = u_1u_2 \in E(G)$ such that $u_1 \in V_1 \setminus \{v_3, v_4\}$ and $u_2 \in V_2$, otherwise $\{v_2, v_4\}$ is a non-isolating cut in *G*, a contradiction. Now we show that *f* is the desired edge. We



Figure 1. The cycle induced by the blue edges is a removable cycle, since it has two vertices of degree 2 in *G*. The edge *uv* is removable. The red and orange (resp. gray) pairs of vertices form a non-isolating (resp. isolating) cut. The green edge is irrelevant.

claim that there exists a path P_1 in $H[V_1 \setminus \{v_3\}]$ between u_1 and v_4 . Since H is 2VC, there exists a path P_1 between u_1 and v_4 not using v_2 . Such path does not use v_3 either since this node is adjacent only to v_2 and v_4 , and $u_1 \notin \{v_3, v_4\}$. If P_1 is not contained in $H[V_1]$, it would need to use at least two edges between V_1 and V_2 in H. However, since there is no edge in H'' between V_1 and V_2 , the only edge in H between V_1 and V_2 is v_4v_5 , so P_1 cannot use two edges between V_1 and V_2 , and thus it must be contained in $H[V_1]$.

Symmetrically, we claim that there exists a path P_2 in $H[V_2 \setminus \{v_1\}]$ between u_2 and v_5 . Notice that $u_2 = v_5$ is possible, in which case the claim trivially holds. Hence, next assume $u_2 \neq v_5$. Observe that $u_2 \neq v_1$ since u_2 is adjacent to $u_1 \notin \{v_2, v_5\}$. Thus, the claim about P_2 follows symmetrically to the case of P_1 . Altogether, v_4v_5 is a chord of the cycle $P_1 \cup P_2 \cup \{f\} \cup C \setminus \{v_4v_5\}$ in $H' = H \cup \{f\}$, which implies the lemma.

We are now ready to define a structured graph and to state our reduction to such graphs (see also Figure 1).

DEFINITION 2.7 (Structured graph). A 2VC graph *G* is structured if it does not contain: (1) Irrelevant edges; (2) Non-isolating cuts, and (3) Removable 5-cycles.

LEMMA 2.8. Given a constant $1 < \alpha \leq \frac{3}{2}$, if there exists a polynomial-time algorithm for 2VCSS on a structured graph *G* that returns a solution of cost at most max{opt(*G*), $\alpha \cdot opt(G) - 2$ }, then there exists a polynomial-time α -approximation algorithm for 2VCSS.

We remark that any $\alpha - \varepsilon$ approximation of 2VCSS on structured graphs, for an arbitrarily small constant $\varepsilon > 0$, immediately implies an algorithm of the type needed in the claim of Lemma 2.8: indeed, instances with $opt(G) \le max\{\frac{2}{\varepsilon}, \frac{2}{\alpha-1}\}$ can be solved exactly in constant time by brute force.

The algorithm at the heart of Lemma 2.8 is algorithm RED given in Figure 1. Lines 1-2 solve instances with few new nodes by brute force. Lines 3-4, 5-10, and 11-12 get rid recursively

	Input: A 2-vertex-connected graph <i>G</i>
	Output: A subgraph <i>H</i> of <i>G</i>
1:	if $ V(G) < \max\{6, \frac{2}{\alpha-1}\}$ then
2:	Compute $OPT(G)$ by brute force (in constant time) and return
	OPT(G)
3:	if G contains an irrelevant edge then
4:	return $RED(G \setminus \{e\})$
5:	if <i>G</i> contains a non-isolating vertex cut { <i>u</i> , <i>v</i> } then
6:	Let $(V_1,V_2), 2 \leq V_1 \leq V_2 $, be a partition of $V(G) \setminus \{u,v\}$ such that
	there are no edges between V_1 and V_2 in $G\setminus\{u,v\}$
7:	Let G_1 be the graph resulting from G by contracting V_2 into
	one node v_2 and ${\cal G}_2$ by contracting V_1 into one node v_1 (keeping
	one copy of parallel edges in both cases)
8:	Let $H_1 = \text{RED}(G_1)$ and $H_2 = \text{RED}(G_2)$
9:	Let E_1 (resp. E_2) be the two edges of H_1 (resp., H_2) with
	endpoints in v_2 (resp., v_1)
10:	return $H := (H_1 \setminus E_1) \cup (H_2 \setminus E_2)$
11:	if G contains a removable 5-cycle then
12:	Let e be the removable edge (found via Lemma 2.6) in that
	cycle and return $RED(G \setminus \{e\})$
13:	return ALG(G)

Algorithm 1. Algorithm RED that reduces from arbitrary to structured instances of 2VCSS. Here *G* is 2VC and ALG is an algorithm for structured instances that returns a solution of cost at most $max{opt(G), \alpha \cdot opt(G) - 2}$ for some $1 < \alpha \le \frac{3}{2}$.

of irrelevant edges, non-isolating vertex cuts and removable 5-cycles, resp. When Line 13 is reached, the graph is structured and therefore we can apply a black-box algorithm ALG for structured instances of 2VCSS.

It is easy to see that the algorithm runs in polynomial time.

LEMMA 2.9. RED(G) runs in polynomial time in |V(G)| if ALG does so.

PROOF. Let n = |V(G)|. First observe that each recursive call, excluding the corresponding subcalls, can be executed in polynomial time. In particular, we can find one irrelevant edge, if any, in polynomial time by enumerating all the possible 2-vertex-cuts. Furthermore, we can find some removable 5-cycle, if any, in polynomial time by enumerating all 5-cycles. Then,

by Lemma 2.6, we can indentify a removable edge in such cycle. We also remark that in Lines 4 and 12 we remove one edge, and we never increase the number of edges. Hence the corresponding recursive calls increase the overall running time by a polynomial factor altogether.

It is then sufficient to bound the number f(n) of recursive calls where we execute Lines 5-10 starting from a graph with n nodes. Consider one recursive call on a graph G with n nodes, where the corresponding graph G_1 has $5 \le k \le n/2 + 2$ nodes. Notice that G_2 has n - k + 4 nodes. Thus, one has $f(n) \le \max_{5\le k \le n/2+2} \{f(k) + f(n-k+4)\}$, which implies that f(n) is polynomially bounded.

Let us next show that RED produces a feasible solution.

LEMMA 2.10. *Given a 2VC graph G*, RED(*G*) *returns a feasible 2VCSS solution for G.*

PROOF. Let us prove the claim by induction on |E(G)|. The base cases are given when RED(G) executes Lines 2 or 13: in these cases RED clearly returns a feasible solution. Consider an instance *G* where RED(G) does not execute those lines (in the root call), and assume the claim holds for any instance *G'* where |E(G')| < |E(G)|. By Lemma 2.2, when RED recurses at Line 4, the graph $G \setminus \{e\}$ is 2VC, hence the recursive call returns a 2VC spanning subgraph by inductive hypothesis. A similar argument holds when Line 12 is executed, this time exploiting Lemma 2.6.

It remains to consider the case when Lines 5-10 are executed. Let us first prove that G_1 and G_2 are 2VC. We prove it for G_1 , the proof for G_2 being symmetric. Assume to get a contradiction that G_1 has a cut vertex w. There must be a path in $G[V_1 \cup \{u, v\}]$ between u and v, otherwise G is not 2VC, so $w \neq v_2$. If $w \in \{u, v\}$, then w is also a cut vertex in G, a contradiction. Therefore $w \in V_1$. If one of the components resulting from removing w from G_1 contains neither u nor v then w is also a cut vertex in G, a contradiction. Thus, removing w from G_1 yields two connected components C_u , C_v , with $u \in C_u$, $v \in C_v$. But the path uv_2v is still present in $G_1 \setminus \{w\}$, contradicting the fact that w is a cut vertex in G_1 .

Notice that $|E(G_1)|$, $|E(G_2)| < |E(G)|$. Since G_1 and G_2 are 2VC, we can assume by inductive hypothesis that both H_1 and H_2 are 2VC. It is left to show that H is 2VC.

Assume to get a contradiction that *H* has a cut vertex *w*. If $w \in \{u, v\}$, then *w* is also a cut vertex in either H_1 or H_2 . Thus we can assume w.l.o.g. $w \in V_1$. Consider the components resulting from removing the vertex *w* from *H*. If one of these components contains neither *u* nor *v* then *w* is also a cut vertex in H_1 . Thus removing *w* from *H* yields two connected components C_u, C_v , with $u \in C_u, v \in C_v$. But since $w \in V_1$, no edge from H_2 present in *H* is removed by deleting *w*. In particular, there is a path from *u* to *v* in *H*, contradicting the fact that *w* is a cut vertex.

It remains to analyze the approximation factor of RED.

$$\textbf{LEMMA 2.11.} |\mathsf{RED}(G)| \le \begin{cases} \mathsf{opt}(G), & if |V(G)| < \max\{6, \frac{2}{\alpha - 1}\}; \\ \alpha \cdot \mathsf{opt}(G) - 2, & if |V(G)| \ge \max\{6, \frac{2}{\alpha - 1}\}. \end{cases}$$

PROOF. We prove the claim by induction on |E(G)|. The base cases correspond to the execution of Lines 2 and 13. Here the claim trivially holds. The claim holds by inductive hypothesis and by Lemmas 2.2 and 2.6 when Lines 4 and 12, resp., are executed. Notice that the 6 that appears in the max in the claim of the lemma is meant to guarantee that the conditions of Lemma 2.6 are satisfied.

It remains to consider the case when Lines 5-10 are executed. Let OPT be a minimum 2VC spanning subgraph of *G*, and OPT_{*i*} be an optimal 2VCSS solution for G_i , $i \in \{1, 2\}$. We will later show:²

$$|\mathsf{OPT}| \ge |\mathsf{OPT}_1| + |\mathsf{OPT}_2| - 4 \tag{1}$$

Notice that, since *G* contains no irrelevant edges, $H_1 \setminus E_1$ and $H_2 \setminus E_2$ are edge-disjoint. Moreover, $|H_i \cap E_i| = 2$ for $i \in \{1, 2\}$, so we have $|H| = |H_1| + |H_2| - 4$. Also, for $|V_i| \ge \frac{2}{\alpha - 1}$, one has $|\mathsf{OPT}_i| \le \alpha |\mathsf{OPT}_i| - 2$, by the induction hypothesis. We now distinguish a few cases.

If $|V_2| < \max\{6, \frac{2}{\alpha-1}\}$, then $|H| = |H_1| + |H_2| - 4 = |\mathsf{OPT}_1| + |\mathsf{OPT}_2| - 4 \le |\mathsf{OPT}|$.

If $|V_1| \ge \max\{6, \frac{2}{\alpha-1}\}$, then $|H| = |H_1| + |H_2| - 4 \le \alpha |\mathsf{OPT}_1| - 2 + \alpha |\mathsf{OPT}_2| - 2 - 4 = \alpha(|\mathsf{OPT}_1| + |\mathsf{OPT}_2|) - 8 \le \alpha |\mathsf{OPT}| + 4\alpha - 8 \le \alpha |\mathsf{OPT}| - 2$. The last inequality uses the assumption $\alpha \le 3/2$.

Finally, if $|V_1| < \max\{6, \frac{2}{\alpha-1}\}$ and $|V_2| \ge \max\{6, \frac{2}{\alpha-1}\}$, we have $|H| = |H_1| + |H_2| - 4 \le |\mathsf{OPT}_1| + \alpha |\mathsf{OPT}_2| - 2 - 4 = (1 - \alpha) |\mathsf{OPT}_1| + \alpha (|\mathsf{OPT}_1| + |\mathsf{OPT}_2|) - 6 \le (1 - \alpha) |\mathsf{OPT}_1| + 4\alpha + \alpha |\mathsf{OPT}| - 6 \le \alpha |\mathsf{OPT}| - 2$. The last inequality holds since $|\mathsf{OPT}_1| \ge |V(G_1)| \ge 5$ and $\alpha > 1$.

It remains to prove (1). Assume by contradiction that $|\mathsf{OPT}| < |\mathsf{OPT}_1| + |\mathsf{OPT}_2| - 4$. Notice that, since *G* contains no irrelevant edges, $E(G) = (E(G_1) \setminus E_1) \dot{\cup} (E(G_2) \setminus E_2)$ and thus $\mathsf{OPT} = ((E(G_1) \setminus E_1) \cap \mathsf{OPT}) \dot{\cup} ((E(G_2) \setminus E_2) \cap \mathsf{OPT})$. Thus we have that either $|(E(G_1) \setminus E_1) \cap \mathsf{OPT}| < |\mathsf{OPT}_1| - 2$ or $|(E(G_2) \setminus E_2) \cap \mathsf{OPT}| < |\mathsf{OPT}_2| - 2$. Assume w.l.o.g. that $|(E(G_1) \setminus E_1) \cap \mathsf{OPT}| < |\mathsf{OPT}_1| - 2$. Then $((E(G_1) \setminus E_1) \cap \mathsf{OPT}) \cup \{uv_2, vv_2\}$ is a 2VC spanning subgraph of G_1 of cardinality less than OPT_1 , a contradiction. (1) follows.

2.2 A Canonical 2-Edge-Cover

It remains to give a good enough approximation algorithm for structured graphs. The first step in our algorithm (similarly to prior work on related problems [6, 19, 25]) is to compute (in polynomial time [33, Chapter 30]) a minimum-cardinality 2-edge-cover³ *H* of *G*. It is worth to

² In fact, it is not difficult to show that (1) holds with equality, but it is not needed for our purposes and therefore we omit it.

³ A 2-edge-cover *H* of a graph *G* is a subset of edges such that each node *v* of *G* has at least 2 edges of *H* incident to it.



Figure 2. Gray regions represent blocks of *H*. C_1 , C_2 and C_3 are small components of *H*, and C_4 and C_5 are large components. Also, C_5 is a complex component. The non-bold edges are bridges of C_5 . The dashed lines encompass the leaf-blocks of C_5 . Notice that C_4 contains a single block, while C_5 contains many of them.

remark that $|H| \le opt(G)$: indeed the degree of each node in any 2VC spanning subgraph of *G* must be at least 2.

For technical reasons, we transform *H*, without increasing its size, into another 2-edgecover which is *canonical* in the following sense. We need some notation first. If a connected component of *H* has at least 6 edges we call it a *large component*, and otherwise a *small component*. Let *C* be a large component of *H*. We call every maximal 2VC subgraph of *C* with at least 3 nodes a *block*, and every edge of *C* such that its removal splits that component into two connected components a *bridge*. Notice that every edge of *C* is either a bridge or belongs to some block in that component. Also, every edge of *C* belongs to at most one block, thus there is a unique partition of the edges of *C* into blocks and bridges (but a node of *C* might belong to multiple blocks and to multiple bridges). Observe that *C* is 2VC iff it has exactly one block. If *C* is large but not 2VC we call it a *complex component*. If a block *B* of a complex component *C* contains only one cut vertex of *C*, we say that *B* is a *leaf-block* of *C*. An example showcasing the notation we use can be found in Figure 2.

Since *H* is a 2-edge-cover, every complex component *C* must have at least 2 leaf-blocks. Indeed, take the block-cutpoint graph C^* of *C*. Since *C* is connected, C^* is a tree, and since *C* is not 2VC, C^* has at least two leafs. Those leafs cannot correspond to a bridge on *C* because *H* is a 2-edge-cover, so they must correspond to leaf-blocks.

DEFINITION 2.12 (Canonical 2-Edge-Cover). A 2-edge-cover *S* of a graph *G* is *canonical* if: (1) Every small component of *S* is a cycle; (2) For any complex component *C* of *S*, each leaf-block *B* of *C* has at least 5 nodes.

LEMMA 2.13. Given a minimum 2-edge-cover H of a structured graph G, in polynomial time one can compute a canonical 2-edge-cover S of G with |S| = |H|.

PROOF. We start with S := H. At each step if there are edges $e \in E(G) \setminus E(S)$ and $e' \in E(S)$, such that $S' := S \cup \{e\} \setminus \{e'\}$ is a 2-edge-cover that has fewer connected components than *S*, or it has the same number of connected components as *S* but has fewer bridges and blocks in total than *S*, then we replace *S* by *S'*. This process clearly terminates within a polynomial number of steps, returning a 2-edge-cover *S* of the same size as the initial *H* (hence in particular *S* must be minimal).

Let us show that the final *S* satisfies the remaining properties. Assume by contradiction that *S* has a connected component *C* with at most 5 edges that is not a cycle. By a simple case analysis *C* must be a 4-cycle plus one chord f. However, this contradicts the minimality of *S*.

Finally assume by contradiction that *S* has a complex component *C*, with a leaf-block *B* such that *B* has at most 4 nodes. By the minimality of *S*, *B* must be a 3-cycle or a 4-cycle. Let $B = v_1 \dots v_k$, $k \in \{3, 4\}$, and assume w.l.o.g. that v_1 is the only cut-vertex of *C* that belongs to *B*. In this case we show that there must exist an edge $e = uz \in E(G)$ such that $u \in \{v_2, v_k\}$ and $z \notin B$. If this is not true then for k = 3, v_1 is a cut-vertex in *G*, and for k = 4, $\{v_1, v_3\}$ form a non-isolating cut, leading to a contradiction in both cases. Consider $S' := S \cup \{e\} \setminus \{uv_1\}$. Note that *S'* is a 2-edge-cover of the same size as *S*. Since uv_1 belongs to a cycle of *S*, then the number of connected components in *S'* is not more than in *S*. If $z \notin C$ the number of connected components of *S'* is less than in *S*, which is a contradiction. Otherwise, the number of connected components of *S* and *S'* is the same. Now in *S'* all the bridges and the blocks of *S* that shared an edge with any path from *u* to *z* in $S \setminus \{uv_1\}$ become part of the same block and all the other bridges and blocks remain the same. This is a contradiction as the total number of bridges and blocks of *S'* is less than in *S*.

2.3 A Credit-Based Argument

Next assume that we are given a minimum-cardinality canonical 2-edge-cover H of a structured graph G. Observe that, for $|H| \le 5$, H is necessarily a cycle of length |H| by the definition of canonical 2-edge-cover. In particular H is already a feasible (and optimal) solution. Therefore, we next assume $|H| \ge 6$. Starting from S = H, we will gradually add edges to (and sometimes remove edges from) S, until S becomes 2VC (see Section 3). In order to keep the size of S under control, we use a credit-based argument similarly to prior work [6, 19, 21]. At high level, the idea is to assign a certain number of credits cr(S) to S. Let us define the cost of S as cost(S) = |S|+cr(S). We guarantee that for the initial value of S, namely S = H, cost(S) $\le \frac{4}{3}|H|$. Furthermore, during the process cost(S) does not increase.

During the process we maintain the invariant that *S* is canonical. Hence, the following credit assignment scheme is valid for any intermediate *S*:



Figure 3. An example of a valid credit assignment. Gray regions represent blocks of *S*. The dashed lines encompass the objects that receive credit (other than bridges). We remark that a large 2VC component receives 2 credits, one credit in the role of a component, and one additional credit in the role of a block of that component.

- 1. To every small component *C* of *S* we assign cr(C) = |E(C)|/3 credits.
- 2. Each large component C receives cr(C) = 1 credits.
- 3. Each block *B* receives cr(B) = 1 credits.
- 4. Each bridge *b* receives cr(b) = 1/4 credits.

An example of such assignment can be seen in Figure 3. We remark that each large connected component *C* of *S* which is 2VC receives one credit in the role of a component, and one additional credit in the role of a block of that component. Let $cr(S) \ge 0$ the total number of credits assigned to the subgraphs of *S*. It is not hard to show that the initial cost of *S* is small enough.

LEMMA 2.14. $cost(H) \le \frac{4}{3}|H|$.

PROOF. Let us initially assign $\frac{1}{4}$ credits to the bridges of H and $\frac{1}{3}$ credits to the remaining edges. Hence, we assign at most $\frac{|H|}{3}$ credits in total. We next redistribute these credits to satisfy the credit assignment scheme.

Each small component *C* retains the credits of its edges. If *C* is large and 2VC then it has exactly one block *B*. Since $|E(C)| \ge 6$, its edges have at least 2 credits, so we can assign 1 credit to *C* and 1 to *B*.

Now consider a complex component *C* of *H*. The bridges keep their own credits. Since *H* is a 2-edge-cover and *C* is complex, then *C* has at least 2 leaf-blocks B_1 and B_2 . By the definition of canonical, B_1 and B_2 have at least 5 nodes (hence edges) each. Therefore, together they have at least $\frac{10}{3} > 3$ credits, which is sufficient to assign one credit to *C*, B_1 and B_2 . Any other block *B* of *C* (which has at least 3 edges) keeps the credits of its edges, hence at least 1 credit. Observe that $cost(H) = |H| + cr(H) \le \frac{4}{3}|H|$ as desired.

As mentioned before, starting from S = H, we will transform S without increasing its cost cost(S) until it becomes a single large component C that is 2VC (and thus it has exactly one

block *B*) and therefore a 2VC spanning subgraph of *G*. Notice that at the end of the process cr(S) = cr(C) + cr(B) = 2, hence $|S| = cost(S) - 2 \le \frac{4}{3}|H| - 2$. Combining this with the trivial case for $|H| \le 5$, we obtain the following lemma.

LEMMA 2.15. Given a canonical minimum 2-edge-cover H of a structured graph G, one can compute in polynomial time a 2VCSS solution S for G with $|S| \le \max\{|H|, \frac{4}{3}|H| - 2\}$.

Given the above results, it is easy to prove Theorem 1.1.

PROOF OF THEOREM 1.1. By Lemma 2.8 it is sufficient to compute a solution of cost at most $\max\{\operatorname{opt}(G), \frac{4}{3} \cdot \operatorname{opt}(G) - 2\}$ on a structured graph *G*. We initially compute a canonical minimum 2-edge-cover *H* of *G* via Lemma 2.13. Then we apply Lemma 2.15 to obtain a 2VCSS solution *S* with $|S| \le \max\{|H|, \frac{4}{3}|H| - 2\} \le \max\{\operatorname{opt}(G), \frac{4}{3}\operatorname{opt}(G) - 2\}$. Clearly all steps can be performed in polynomial time.

It remains to discuss the proof of Lemma 2.15 (assuming $|H| \ge 6$), which is the most technical part of our paper. The construction at the heart of the proof consists of a few stages. Recall that we start with a 2-edge-cover S = H, and then gradually transform S without increasing cost(S). We now define a specific type of 4-cycles that need special care.

DEFINITION 2.16 (pendant 4-cycle). Let *S* be a 2-edge-cover of a graph *G* and *C'* be a large component of *S*. We say that a connected component *C* of *S* is a *pendant* 4-cycle (of *C'*) if *C* is a 4-cycle and all the edges of *G* with exactly one endpoint in V(C) have the other endpoint in V(C').

In the initial phase of our construction (see Section 3.1), we eliminate all small components from *S*, except for pendant 4-cycles. Pendant 4-cycles are harder to remove, and thus they require separate arguments. They will be dealt with in later stages of the algorithm.

LEMMA 2.17. Let *G* be a structured graph and *H* be a canonical minimum 2-edge cover of *G*, with $|H| \ge 6$. In polynomial time one can compute a canonical 2-edge-cover *S* of *G* such that the only small components of *S* are pendant 4-cycles and $cost(S) \le cost(H)$.

In the second stage of our construction (see Section 3.2) we reduce to the case where *S* consists of large 2VC components only.

LEMMA 2.18. Let G be a structured graph and S be a canonical 2-edge-cover of G such that the only small components of S are pendant 4-cycles. In polynomial time one can compute a canonical 2-edge-cover S' of G such that all the connected components of S' are 2VC and large, and $cost(S') \le cost(S)$.

At this point we can exploit the following definition and lemma from [19] (see Figure 4) to construct the desired 2VC spanning subgraph.



Figure 4. An example of nice cycles w.r.t. the partition ⊓ (induced by the dashed lines). In the figure two distinct nice cycles are shown, given by the red and blue edges, respectively.

DEFINITION 2.19 (Nice Cycle). Let $\Pi = (V_1, \ldots, V_k)$, $k \ge 2$, be a partition of the node-set of a graph *G*. A nice cycle *N* of *G* w.r.t. Π is a subset of edges with endpoints in distinct subsets of Π such that: (1) *N* induces one cycle of length at least 2 in the graph obtained from *G* by collapsing each V_i into a single node; (2) given the two edges of *N* incident to some V_i , these edges are incident to distinct nodes of V_i unless $|V_i| = 1$.

LEMMA 2.20. [19] Let $\Pi = (V_1, \ldots, V_k)$, $k \ge 2$, be a partition of the node-set of a 2VC graph G. In polynomial time one can compute a nice cycle N of G w.r.t. Π .

LEMMA 2.21. Let G be a structured graph and S be a 2-edge-cover of G such that all the connected components of S are 2VC and large. In polynomial time one can compute a 2VCSS solution S' for G with $cost(S') \le cost(S)$.

PROOF. Initially set S' = S. Consider the partition $\Pi = (V_1, \ldots, V_k)$ of V(G) where V_i is the set of vertices of the 2VC component C_i of S'. If k = 1, S' already satisfies the claim. Otherwise, using Lemma 2.20 we can compute a nice cycle N of G w.r.t. Π . Let us replace S' with $S'' := S' \cup N$. W.l.o.g assume N is incident to V_1, \ldots, V_r for some $2 \le r \le k$. Then in S'' the nodes $V_1 \cup \ldots \cup V_r$ belong to a unique (large) 2VC connected component C'. Furthermore $cost(S') - cost(S'') = \sum_{i=1}^{r} (cr(C_i) + cr(B_i)) - cr(C') - cr(B') - r = 2r - 2 - r \ge 0$, where B_i is the only block of the component C_i and B' the only block of C'. By iterating the process for a polynomial number of times one obtains a single 2VC component, hence the claim.

The proof of Lemma 2.15 follows by chaining Lemmas 2.17, 2.18, and 2.21, and by the previous simple observations.

3. From a Canonical 2-Edge-Cover to a 2VC Spanning Subgraph

In the following two subsections we provide the proof of Lemmas 2.17 and 2.18, hence completing the proof of Lemma 2.15. Throughout this section, we say that two connected components C_1 and C_2 of S are *adjacent* if there are nodes $u_1 \in C_1$, $u_2 \in C_2$ such that $u_1u_2 \in E(G)$.

We will use following lemma from [19] multiple times, whose proof is duplicated here for the sake of completeness.

LEMMA 3.1 (3-Matching Lemma). Let G = (V, E) be a 2VC graph without irrelevant edges and without non-isolating 2-vertex-cuts. Consider any partition (V_1, V_2) of V such that for each $i \in \{1, 2\}, |V_i| \ge 3$ and if $|V_i| = 3$, then $G[V_i]$ is a triangle. Then, there exists a matching of size 3 between V_1 and V_2 .

PROOF. Consider the bipartite graph *F* induced by the edges with exactly one endpoint in V_1 . Let *M* be a maximum (cardinality) matching of *F*. Assume by contradiction that $|M| \le 2$. By König-Egeváry theorem⁴ there exists a vertex cover *U* of *F* of size |M|. We distinguish 3 subcases:

(1) $U = \{u\}$. Assume w.l.o.g. $u \in V_1$. Since U is a vertex cover of F, there are no edges in F (hence in G) between the non-empty sets $V_1 \setminus \{u\}$ and V_2 . Hence U is a 1-vertex-cut, a contradiction.

(2) $U = \{u, v\}$, where U is contained in one side of F. Assume w.l.o.g. $U \subseteq V_1$. Since $|V_1| \ge 3$ and U is a vertex cover of F, U is a 2-vertex-cut separating $V_1 \setminus U$ from V_2 . This implies that $uv \notin E(G)$ (otherwise uv would be an irrelevant edge), and in particular that $G[V_1]$ is not a triangle. Since $G[V_1]$ is not a triangle, $|V_1 \setminus U| \ge 2$. This implies that U is a non-isolating 2-vertex-cut of G, a contradiction.

(3) $U = \{u, v\}$, where u and v belong to different sides of F. Assume w.l.o.g. $u \in V_1$ and $v \in V_2$. Consider the sets $V'_1 := V_1 \setminus \{u\}$ and $V'_2 := V_2 \setminus \{v\}$, both of size at least 2. Notice that there are no edges in F (hence in G) between V'_1 and V'_2 (otherwise U would not be a vertex cover of F). This implies that U is a non-isolating 2-vertex-cut of G, a contradiction.

3.1 Removing almost all small components

In this section we will prove Lemma 2.17, namely we will show how to get rid of small components other than pendant 4-cycles. Recall that a connected component is large if it contains at least 6 edges and small otherwise. In our construction we will maintain that *S* is canonical, hence in particular small components of the considered partial solution *S* are cycles (of size 3, 4 or 5).

We distinguish two types of small components that we deal with separately: small components that are adjacent to at least 2 connected components of *S*, and small components adjacent only to a single connected component of *S* (excluding pendant 4-cycles). Let us start by handling the former type of small components. This is done via the following lemma.

LEMMA 3.2. Let *S* be a canonical 2-edge-cover of a structured graph *G*. If *S* contains a small component adjacent to at least two other connected components of *S*, then one can compute in polynomial time a canonical 2-edge-cover *S'* of *G*, with strictly fewer components than *S*, and with $cost(S') \le cost(S)$.

⁴ This theorem states that, in a bipartite graph, the cardinality of a maximum matching equals the cardinality of a minimum vertex cover, see e.g. [**33, Chapter 16**].

In order to prove the above lemma, we need the following definition and intermediate results.

DEFINITION 3.3. Let *C* be a *k*-cycle, $k \in \{3, 4, 5\}$. We say that $\{u, v\} \subseteq V(C)$ is a *shortcut pair* of *C* if there is a matching *M* of size 2 from $\{u, v\}$ to $V(G) \setminus V(C)$, and there is a *u*-*v* Hamiltonian path P_{uv} in G[V(C)] such that the first and last edge of P_{uv} are in E(C). We call *M* the *corresponding matching* of $\{u, v\}$ and P_{uv} the *shortcut path* of $\{u, v\}$ or the shortcut path of *C* if $\{u, v\}$ is clear from the context.

Shortcut pairs play an important role in the proof of Lemma 3.2. Intuitively, once we find a shortcut pair $\{u, v\}$ of a small component *C* with corresponding matching $\{ux, vy\}$, we can exchange the edges of *C* with its shortcut path (hence "saving" one edge), thus getting a path from *x* to *y* that includes all the nodes of *C*. We will use this to "chain" together several small components in order to build a path between components of *S* with some desired properties. The next lemma shows that we can always find a shortcut pair of a small component. Additionally, it shows that we can choose such pair in a way that allows us to continue building the aforementioned path.

LEMMA 3.4. Let *S* be a canonical 2-edge-cover of a structured graph *G*, *C* be a small component of *S*, and wx be an edge of *G* such that $w \in V(C)$, $x \notin V(C)$. Then there exists a shortcut pair $\{u, v\}$ such that ux is an edge of the corresponding matching of $\{u, v\}$. Furthermore, if *C* is a 3-cycle, there exist two distinct shortcut pairs $\{u, v_1\}$, $\{u, v_2\}$ such that their corresponding matchings are $\{ux, v_1w_1\}$ and $\{ux, v_2w_2\}$, $w_1 \neq w_2$, resp. All such pairs and their corresponding matchings and shortcut paths can be computed in polynomial time.

PROOF. By the 3-matching Lemma 3.1 applied to *C*, there is a matching $\{w_1x_1, w_2x_2, w_3x_3\}$, with $x_i \notin V(C), w_i \in V(C)$, for $i \in \{1, 2, 3\}$. W.l.o.g. we can assume $x_1 = x$, indeed otherwise we can add wx to the matching and remove wx_i if any. If *C* is a 3-cycle, the pairs $\{u, v_1\} = \{w_1, w_2\}$ and $\{u, v_2\} = \{w_1, w_3\}$ are the desired pairs, with shortcut paths $P_{uv_1} = C \setminus \{uv_1\}$ and $P_{uv_2} = C \setminus \{uv_2\}$, resp.

Assume next that *C* is a 4-cycle or a 5-cycle. If w_i is adjacent to w_1 in *C* for some $i \in \{2, 3\}$ then $\{u, v\} = \{w_1, w_i\}$ is the desired shortcut pair, with corresponding matching $\{ux, vx_i\}$ and shortcut path $P_{uv} = C \setminus \{uv\}$. Notice that this is always the case if *C* is a 4-cycle. We next assume that $w_i, i \in \{2, 3\}$, is not adjacent to w_1 in *C* (and thus *C* is a 5-cycle). Moreover, we can assume that there is no matching $M = \{w'_1x, w'_2x'_2\}$, where $x'_2 \notin V(C), w'_1, w'_2 \in V(C)$, and w'_1 is adjacent to w'_2 in *C*.

Let $C = w_1 a w_2 w_3 b$. Notice that by the above assumption there cannot exist an edge $ay \in E(G)$ with $y \notin V(C)$. Indeed, if $y \neq x$, then the matching $M = \{w_1 x, ay\}$ is a contradiction to our above assumption, and if y = x then the matching $M = \{ax, w_2 x_2\}$ is a contradiction to our above assumption. Symmetrically, b is not adjacent to any node outside C in G.

Since *G* is a structured graph, *C* is not a removable 5-cycle, and thus either *a* or *b*, say *a* by symmetry, is adjacent in *G* to some node in *C* other than w_1 and w_2 . We claim that $\{u, v\} = \{w_1, w_2\}$ is our desired shortcut pair, with its corresponding matching $\{ux, vx_2\}$. If $ab \in G$ then $P_{uv} = w_1 abw_3 w_2$ satisfies the claim. If $ab \notin E(G)$, then it must be $w_3a \in E(G)$. Hence $P_{uv} = w_1 bw_3 aw_2$ satisfies the claim.

COROLLARY 3.5. Let *S* be a canonical 2-edge-cover of *G* and *C* be a small component of *S*. If *C* is adjacent to at least two other connected components of *S*, then we can find in polynomial time a shortcut pair $\{u, v\}$ of *C* such that its corresponding matching $\{ux_1, vx_2\}$ has $x_1 \in V(C_1), x_2 \in V(C_2)$, where *C*, C_1 and C_2 are distinct connected components of *S*.

PROOF. We first claim that there are edges ax_1 , bx_2 with $a, b \in V(C)$, $x_1 \in V(C_1)$, $x_2 \in V(C_2)$, $a \neq b$, where C_1 and C_2 are distinct connected components of S. To obtain this, we apply the 3-matching Lemma 3.1 to C. If two edges of the matching have their endpoints not in C in distinct connected components of S we are done. Otherwise, all edges of the matching are incident to the same connected component C'. By assumption of the lemma there is at least one edge between C and a connected component of S distinct from C', so we can modify the matching by including that edge and removing at most one edge. The claim follows.

Apply Lemma 3.4 to ax_1 and bx_2 to find shortcut pairs of C, $\{u_1, v_1\}$, $\{u_2, v_2\}$, such that u_1x_1, u_2x_2 belong to their respective corresponding matchings. If the corresponding matching $\{u_1x_1, v_1y_1\}$ has $y_1 \notin V(C_1)$, then $\{u, v\} = \{u_1, v_1\}$ is the desired shortcut pair. Similarly for the corresponding matching to $\{u_2, v_2\}$, $\{u_2x_2, v_2y_2\}$. Assume now that $y_1 \in V(C_1)$, $y_2 \in V(C_2)$.

If $u_1 = u_2$, then $\{u, v\} = \{u_1, v_2\}$ is the desired shortcut pair. Similarly with $u_1 = v_2, v_1 = u_2, v_1 = v_2$. Assume u_1, v_1, u_2, v_2 are all distinct. Then either u_1 is adjacent in *C* to one of u_2 or v_2 , or v_1 is. Say u_1 is adjacent to u_2 . The shortcut pair $\{u, v\} = \{u_1, u_2\}$ satisfies the claim with matching $\{u_1x_1, u_2x_2\}$ and $P_{uv} = C \setminus \{uv\}$. The other cases are treated identically, with the corresponding matchings being $\{u_1x_1, v_2y_2\}, \{v_1y_1, u_2x_2\}$, and $\{v_1y_1, v_2y_2\}$.

We are now ready to prove Lemma 3.2.

PROOF OF LEMMA 3.2. We next describe an iterative procedure to construct a (maximal in some sense) path *P*, incident on two distinct connected components C_L and C_R of *S*. Formally, Algorithm 2 finds, in polynomial time, a path $P = u_L u_1 u_2 \dots u_k u_R$ satisfying the following properties:

- 1. $|E(P)| \ge 4$.
- 2. The set $\{u_1, \ldots, u_k\}$ of internal nodes of *P* is the union of the node sets of some small components of *S*. The nodes u_L, u_R belong to distinct connected components C_L, C_R of *S*.
- 3. If C_L is small, then for some $v_L \in V(C_L)$, $\{u_L, v_L\}$ is a shortcut pair of C_L such that its corresponding matching is $\{u_L u_1, v_L w_L\}$, with $w_L \in V(C_R) \cup V(P)$. Moreover, if C_L is a 3-cycle, then $w_L \neq u_3$.

	Input: A canonical 2-edge-cover <i>S</i> of a structured graph <i>G</i>
	containing a small component C adjacent to at least two
	other components of S
	Output: A path <i>P</i> between connected components of <i>S</i> satisfying
	Properties 1 to 5.
1:	Initialization: Let $\{u, v\}$ be a shortcut pair of C with shortcut
	path P_{uv} and corresponding matching $\{uu_L, vu_R\}$, $u_L \in V(C_L)$, $u_R \in V(C_R)$,
	where C_L and C_R are distinct connected components of S
2:	$P \leftarrow P_{uv} \cup \{uu_L, vu_R\}$
3:	while C _L is small do
4:	if there exists a shortcut pair $\{u,v\}$ of C_L with shortcut path
	P_{uv} and corresponding matching $\{uu_1, vx\}$ such that $x \notin V(C_R) \cup V(P)$
	then
5:	Let C'_L be the component of S such that $x \in V(C'_L)$
6:	$P \leftarrow (E(P) \setminus \{u_1u_L\}) \cup E(P_{uv}) \cup \{uu_1, vx\}$
7:	$C_L \leftarrow C'_L$ > Extension on the left side (see Figure 5)
8:	else
9:	Let $\{u, v\}$ be a shortcut pair of C_L with corresponding
	matching $\{uu_1, vx\}$ such that $x \in V(C_R) \cup V(P)$. If C_L is a
	3-cycle, choose such a pair such that $x \neq u_3$
10:	$P \leftarrow (E(P) \setminus \{u_1u_L\}) \cup \{uu_1\}$ \triangleright Stop the extension on the left side (see Figure 6)
11:	break > We exit the while loop
12:	while C _R is small do
13:	if there exists a shortcut pair $\{u,v\}$ of C_R with shortcut path
	P_{uv} and corresponding matching $\{uu_k, vx\}$ such that $x \notin V(C_L) \cup V(P)$
	then
14:	Let C'_R be the component of S such that $x \in V(C'_R)$
15:	$P \leftarrow (E(P) \setminus \{u_k u_R\}) \cup E(P_{uv}) \cup \{u u_k, vx\}$
16:	$C_R \leftarrow C'_R$ Extension on the right side
17:	else
18:	Let $\{u, v\}$ be a shortcut pair of C_R with corresponding
	matching $\{uu_k, vx\}$ such that $x \in V(C_L) \cup V(P)$. If C_R is a
	3-cycle, choose such a pair such that $x \neq u_{k-2}$
19:	$P \leftarrow (E(P) \setminus \{u_k u_R\}) \cup \{u u_k\}$ > Stop the extension on the right side
20:	break > We exit the while loop
21:	return P

Algorithm 2. Algorithm that computes *P*. During the execution of the algorithm, at the beginning of every iteration of a while loop, we maintain the notation that $P = u_L u_1 \dots u_k u_R$, $u_L \in V(C_L)$, $u_R \in V(C_R)$.

- 4. If C_R is small, then for some $v_R \in V(C_R)$, $\{u_R, v_R\}$ is a shortcut pair of C_R such that its corresponding matching is $\{u_R u_1, v_R w_R\}$, with $w_R \in V(C_L) \cup V(P)$. Moreover, if C_R is a 3-cycle, then $w_R \neq u_{k-2}$.
- 5. The edges u_1u_2 and $u_{k-1}u_k$ are edges of small components of *S*.

Since at every iteration the length of *P* increases or a while loop stops, Algorithm 2, terminates after a polynomial number of iterations. By Corollary 3.5, one can find the shortcut pair required in Line 1 in polynomial time. The condition in Line 4 can be checked in polynomial time by considering all pairs of nodes of C_L (recall C_L is small when executing Line 4) and all matchings of size 2 incident to such pairs. When executing Line 9, by Lemma 3.4 and the fact that the condition at Line 4 does not hold, we can find the desired pair. Notice that here we used the fact that, if C_L is a 3-cycle, Lemma 3.4 guarantees the existence of two shortcut pairs $\{u, v_1\}, \{u, v_2\}$ with corresponding matchings $\{uu_1, v_1w_1\}$ and $\{uu_1, v_2w_2\}, w_1 \neq w_2$. Since the condition at Line 4 does not hold, $w_1, w_2 \in V(C_R) \cup V(P)$, so we can choose $v = v_i$ such that $w_i \neq u_3$, for some $i \in \{1, 2\}$. The executions of Lines 13 and 18 can also be done in polynomial time by identic arguments. Therefore, Algorithm 2 runs in polynomial time.

Now we show that *P* satisfies Properties 1 to 5. Property 1 is satisfied when initializing *P* at Line 2, and is maintained through the execution of the algorithm because we never decrease the size of *P*. Notice that *P* satisfies Property 2 at Line 2. The set of internal nodes of *P* then only changes at Lines 7 and 16. When executing those lines, we add the nodes of the shortcut path P_{uv} of C_L (resp., C_R) to the set of internal nodes of *P*. Since when executing Line 7 (resp., 16) C_L (resp., C_R) is small, we maintain Property 2. Properties 3 and 4 are satisfied by the choice of $\{u, v\}$ at Lines 9 and 18, respectively. Finally, notice that the edges u_1u_2 and $u_{k-1}u_k$ are the last edges of some shortcut path of some small component. Thus, by Definition 3.3, they are edges of small components of *C*. Therefore, *P* satisfies Properties 1 to 5, as we wanted to prove.

Next we build *S'* as follows. Let C_1, \ldots, C_q be the small components whose node sets form the internal nodes of *P* (Property 2). We initially set $S' := (S \setminus \bigcup_{i=1}^q E(C_i)) \cup E(P)$. If C_L is small, let $\{u_L, v_L\}$ be the shortcut pair given by Property 3, with matching $\{u_L u_1, v_L w_L\}$ and shortcut path $P_{u_L v_L}$: replace *S'* with $(S' \setminus E(C_L)) \cup P_{u_L v_L} \cup \{v_L w_L\}$. If C_R is small, we update *S'* symmetrically (using Property 4). We will use figures to show examples of the construction of *S'* based on *P* in the corresponding relevant cases.

Notice that |S'| = |S| + 1. We also remark that we collect $(|E(P)| - 1) \cdot \frac{1}{3}$ credits from the removed small components. Clearly S' has fewer connected components than S and is canonical. We will show that in most cases $cost(S') \le cost(S)$. When the latter property does not hold, we will describe an alternative S' that satisfies the claim. We consider different cases depending on the type of the components C_R and C_L .

(1) Both C_R and C_L are large.

An example of the construction of S' for this case is shown in Figure 7. S' contains a (complex)



Figure 5. An example of extending *P* on the C_L side. The shortcut path P_{uv} of C_L is shown in bold blue. In this iteration we remove $u_L u_1$ (in red) from *P*, and add P_{uv} , $u_1 u$ and vx (all of them in blue) to *P*. Here C'_L could be small or large. In the next iteration C'_L takes the place of C_L .



Figure 6. In this case we stop extending *P* on the left side. Notice that in this case we have at least 2 choices for the pair $\{u, v\}$. Since C_L is a 3-cycle we select the pair $\{u, v\}$ such that $x \neq u_3$. The dashed edges are edges in *G*.

connected component *C* spanning the nodes of C_R , C_L and *P*. We need 1 credit for *C* and $|E(P)| \cdot \frac{1}{4}$ credits for the edges of *P* (which become bridges of *C*). Recall that we collect $(|E(P) - 1|) \cdot \frac{1}{3}$ credits from the removed small components. We also collect 1 credit from C_R and C_L each, while their blocks retain their credits. Altogether

$$cost(S) - cost(S') = |S| - |S'| + cr(C_R) + cr(C_L) + (|E(P)| - 1) \cdot 1/3 - cr(C) - |E(P)| \cdot 1/4$$
$$= -1 + 1 + (|E(P)| - 1) \cdot 1/3 - 1 - |E(P)| \cdot 1/4 \ge 0,$$

where in the last inequality we used $|E(P)| \ge 4$ (Property 1).



Figure 7. An example of the construction of *S'* when both C_L and C_R are large components. The set of internal nodes of *P* is the union of the node sets of some small components C_1, \ldots, C_q of *S*. In this case we simply set $S' := (S \setminus \bigcup_{i=1}^q E(C_i)) \cup E(P)$. Every connected component $C \notin \{C_L, C_R\} \cup \{C_1, \ldots, C_q\}$ of *S* remains unaltered.



Figure 8. An example of the construction of S' when C_L is a small component and $w_L \in V(C_R)$. We show the case in which C_R is also a small component. We remove the edges of C_L and C_R , and we add their shortcut paths and the edges $v_L w_L$ and $v_R w_R$. This is equivalent to removing the red edges and adding the blue edges. The shortcut paths of C_L and C_R are shown in bold blue. In this case every node of P and C_L belongs to a block B in S'. If C_R is small, the nodes of C_R also belong to B. The set of internal nodes of P is the union of the node sets of some small components C_1, \ldots, C_q of S. Every connected component $C \notin \{C_L, C_R\} \cup \{C_1, \ldots, C_q\}$ of S remains unaltered.

(2) At least one among C_R and C_L is small (w.l.o.g. assume C_L is small).

Notice that, by Property 3, one has that $w_L \in V(C_R) \cup V(P) \setminus \{u_1\}$, so that either $w_L \in V(C_R)$ or $w_L = u_j$ for some $j \in \{2, ..., k\}$.

$(2.1) w_L \in V(C_R).$

An example of the construction of S' for this case is shown in Figure 8. Regardless of the type of component C_R is, the nodes of C_R , C_L and P are merged into a unique large component C of S', and the nodes of C_L and P belong to a block B in S'. Therefore the edges of P are not bridges in C and hence have no credits in S'.

If C_R is also a small component the nodes of C_R (and thus all nodes of C) also belong to B, so B is the only new block. To see this, notice that all the nodes of the path from w_R to u_R in S'belong to a block B' together with the nodes of C_R . Since $w_R \in V(C_L) \cup V(P)$ (Property 4), this implies that B and B' share at least one edge, and thus it must be that B = B'. If C_R is a large component, then B is also the only block of S' not present in S. Using $|E(P)| \ge 4$ (Property 1) one has

$$cost(S) - cost(S') = |S| - |S'| + cr(C_R) + cr(C_L) + (|E(P)| - 1) \cdot 1/3 - cr(C) - cr(B)$$

$$\geq -1 + 1 + 1 + (|E(P)| - 1) \cdot 1/3 - 1 - 1 \geq 0.$$

(2.2) $w_L = u_2$.

We illustrate this case in Figure 9. Let *C* be the component of *S* such that $w_L \in C$. By Property 5, $u_1u_2 \in E(C)$. Let $S'' := (S \setminus E(C_L)) \cup E(P_{u_Lv_L}) \cup \{u_Lu_1, v_Lu_2\} \setminus \{u_1u_2\}$. In *S*", the nodes of *C* and *C*_L belong to a single cycle *C*' of size at least 6: *C*' is a 2VC large component, and thus it contains exactly one block *B*. Then, *S*" is a solution with fewer components than *S* and one has

$$cost(S) - cost(S'') = cr(C_L) + cr(C) - cr(C') - cr(B) \ge 1 + 1 - 1 - 1 = 0.$$



Figure 9. Lemma 3.2 Case 2. By Property 5, the edge u_1u_2 belongs to some small component *C* of *S*. Note that $u_3u_4 \in E(P)$. We can add the blue edges and remove the red edges from *S* to merge two small components into a large one.



Figure 10. An example of the construction of *S'* when C_L is a small component, $w_L = u_j$, $j \in \{3, ..., k\}$ and C_R is a large component. We remove the edges of C_L and we add the shortcut path of C_L and the edge $v_L w_L$. This is equivalent to removing the red edge and adding the blue edges. The shortcut path of C_L is shown in bold blue. The nodes of C_L together with the path $u_L u_1 u_2 ... u_j$ and the edge $v_L u_j$ belong to a block B_L in *S'*. The set of internal nodes of *P* is the union of the node sets of some small components $C_1, ..., C_q$ of *S*. Every connected component $C \notin \{C_L, C_R\} \cup \{C_1, ..., C_q\}$ of *S* remains unaltered.

(2.3) $w_L = u_j, j \in \{3, ..., k\}.$ (2.3.1) C_R is a large component.

An example of the construction of S' for this case is shown in Figure 10. S' contains a complex connected component C spanning the nodes of C_R , C_L and P. The nodes of C_L together with the path $u_L u_1 u_2 \dots u_j$ and the edge $v_L u_j$ belong now to a block B_L in S', so exactly |E(P) - j| edges of P are now bridges of C, and require $\frac{1}{4}$ credit each. If C_L is not a 3-cycle one has

$$cost(S) - cost(S') ≥$$

|S| - |S'| + cr(C_R) + cr(C_L) + (|E(P)| - 1) · 1/3 - cr(C) - cr(B_L) - (|E(P)| - j) · 1/4 ≥
- 1 + 1 + 4/3 + (|E(P)| - 1) · 1/3 - 1 - 1 - (|E(P)| - 3) · 1/4 > 0.

On the other hand, if C_L is a 3-cycle by Property 3 we can assume $j \ge 4$, so one has

$$cost(S) - cost(S') \ge |S| - |S'| + cr(C_R) + cr(C_L) + (|E(P)| - 1) \cdot 1/3 - cr(C) - cr(B_L) - (|E(P)| - j) \cdot 1/4 \ge -1 + 1 + (|E(P)| - 1) \cdot 1/3 - 1 - 1 - (|E(P)| - 4) \cdot 1/4 \ge 0.$$

In both cases we used Property 1, i.e., $|E(P)| \ge 4$.

(2.3.2) C_R is a small component.

An example of the construction of S' for this case is shown in Figure 11. S' contains a large component C spanning the nodes of C_R , C_L and P. If in S' the nodes of C_R , C_L and P belong to a single block B then one has

$$cost(S) - cost(S') = |S| - |S'| + cr(C_R) + cr(C_L) + (|E(P)| - 1) \cdot 1/3 - cr(C) - cr(B)$$

$$\geq -1 + 1 + 1 + 1 - 1 - 1 = 0,$$

where we have used $|E(P)| \ge 4$ (Property 1). Otherwise, *C* is a complex component. As in the previous case, the nodes of C_L together with the path $u_L u_1 u_2 \dots u_j$ and the edge $v_L u_j$ belong now to a block B_L in *S'*. By the symmetry of Properties 1 to 5 w.r.t. C_L and C_R , we can assume that the nodes of C_R together with the subpath of *P*, $u_R u_k u_{k-1} \dots u_{k-j'}$ and an edge $v_R u_{k-j'}$ belong now to a block B_R , where $j' \ge 3$ and $k - j' \ge j$ (otherwise B_R and B_L would share an edge in *S'* and thus *C* would not be a complex component). Notice that we have $|E(P)| \ge j + j'$. If C_L is not a 3-cycle one has

$$cost(S) - cost(S') = |S| - |S'| + cr(C_R) + cr(C_L) + (|E(P)| - 1) \cdot 1/3$$

- cr(C) - cr(B_R) - cr(B_L) - (|E(P)| - j - j') \cdot 1/4
$$\geq -1 + 1 + 4/3 + (|E(P)| - 1) \cdot 1/3 - 1 - 1 - 1 - (|E(P)| - 6) \cdot 1/4 \geq 0.$$

The last inequality above follows from the fact that $|E(P)| \ge j + j' \ge 6$. If C_L is a 3-cycle we can assume by Property 3 that $j \ge 4$ and one has

$$cost(S) - cost(S') = |S| - |S'| + cr(C_R) + cr(C_L) + (|E(P)| - 1) \cdot 1/3$$

- cr(C) - cr(B_R) - cr(B_L) - (|E(P)| - j - j') \cdot 1/4
$$\geq -1 + 1 + (|E(P)| - 1) \cdot 1/3 - 1 - 1 - (|E(P)| - 7) \cdot 1/4 \geq 0.$$

The last inequality above follows from the fact that $|E(P)| \ge j + j' \ge 7$.

We next address the small components of the second type, i.e., small components adjacent only to a single connected component of *S* (excluding pendant 4-cycles).

LEMMA 3.6. Let *S* be a canonical 2-edge-cover of a structured graph *G*. Assume that *S* contains a small component *C* such that *C* is only adjacent to another component *C*' of *S* and *C* is not a



Figure 11. An example of the construction of *S'* when C_L is a small component, $w_L = u_j$, $j \in \{3, ..., k\}$ and C_R is also a small component. We remove the edges of C_L and C_R , and we add their shortcut paths and the edges $v_L w_L$ and $v_R w_R$. This is equivalent to removing the red edges and adding the blue edges. The shortcut paths of C_L and C_R are shown in bold blue. The nodes of C_L together with the path $u_L u_1 u_2 ... u_j$ and the edge $v_L w_L$ belong to a block B_L in *S'*. Similarly, the nodes of C_R together with the path $u_R u_R u_{R-1} ... u_{R-j'}$ and the edge $v_R w_R$ belong to a block B_R in *S'*. In the case shown, $B_L \neq B_R$. The set of internal nodes of *P* is the union of the node sets of some small components $C_1, ..., C_q$ of *S*. Every connected component $C \notin \{C_L, C_R\} \cup \{C_1, ..., C_q\}$ of *S* remains unaltered.

pendant 4-cycle. Then one can compute in polynomial time a canonical 2-edge-cover S' of G with strictly fewer components than S and with $cost(S') \le cost(S)$.

PROOF. Apply the 3-matching Lemma 3.1 to *C* to get a matching $\{u_1v_1, u_2v_2, u_3v_3\}, u_i \in C, v_i \in C'$ for $i \in \{1, 2, 3\}$. W.l.o.g. assume that u_1 and u_2 are adjacent in *C*. This way, $E(C) \cup \{u_1v_1, u_2v_2\} \setminus \{u_1u_2\}$ is a path from v_1 to v_2 whose internal nodes are given by V(C). We will consider a few cases depending on the type of *C* and *C'*.

(1) *C*′ is small.

(1.1) At least one among C and C' is a 3-cycle or both C and C' are 4-cycles.

In this case w.l.o.g. we can assume that v_1 and v_2 are adjacent in C'. Let $S' := S \cup \{u_1v_1, u_2v_2\} \setminus \{u_1u_2, v_1v_2\}$. Notice that $E(C) \cup E(C') \cup \{u_1v_1, u_2v_2\} \setminus \{u_1u_2, v_1v_2\}$ induces a cycle C'' of length at least 6 in S' (hence a 2VC large component with a single block B). One has

$$cost(S) - cost(S') = cr(C) + cr(C') - cr(C'') - cr(B) \ge 1 + 1 - 1 - 1 = 0.$$

(1.2) At least one among *C* and *C'* is a 5-cycle.

Assume that C' is a 5-cycle, the other case being symmetric. By Case 1 we can assume that C is a 4-cycle or a 5-cycle. Set $S' := S \cup \{u_1v_1, u_2v_2\} \setminus \{u_1u_2\}$. Notice that C and C' are merged into a 2VC large component C'' of S' with a single block B. One has

$$cost(S) - cost(S') = cr(C) + cr(C') - cr(C'') - cr(B) - 1 \ge 4/3 + 5/3 - 1 - 1 - 1 = 0.$$

(2) *C*′ is large.

Observe that *C* is a 3-cycle or a 5-cycle since by assumption it is not a pendant 4-cycle.

(2.1) *C* is a 5-cycle.

(2.1.1) There is a v_1 - v_2 path P in C' that includes some edge of some block or at least 2 bridges. Set $S' := S \cup \{u_1v_1, u_2v_2\} \setminus \{u_1u_2\}$. Let C'' be the connected component of S' that includes the nodes of *C* and *P*. If *P* includes an edge of some block *B* in *S*, then in *S*' the nodes of *C*, *P* and *B* belong to a single block *B*', and one has:

$$cost(S) - cost(S') \ge |S| - |S'| + cr(C) + cr(B) - cr(B') = -1 + \frac{5}{3} + 1 - 1 > 0.$$

Otherwise, *P* includes at least 2 bridges, so we get at least $2 \cdot \frac{1}{4} = \frac{1}{2}$ credits from the bridges along *P*. Also, the nodes of *C* and *P* form a new block *B*', which is the only block in *S*' not present in *S*. Altogether

$$cost(S) - cost(S') \ge |S| - |S'| + cr(C) + \frac{1}{2} - cr(B') = -1 + \frac{5}{3} + \frac{1}{2} - 1 > 0$$

(2.1.2) v_1v_2 is a bridge of C'.

Set $S' := S \cup \{u_1v_1, u_2v_2\} \setminus \{u_1u_2, v_1v_2\}$. In S' we replace the bridge v_1v_2 with a path P of |E(C)| + 1 bridges. One has

$$\cos(S) - \cos(S') = \operatorname{cr}(C) + \operatorname{cr}(v_1v_2) - \sum_{e \in E(P)} \operatorname{cr}(e) = |E(C)| \frac{1}{3} + \frac{1}{4} - (|E(C)| + 1) \frac{1}{4} \ge 0.$$

(2.2) *C* is a 3-cycle.

(2.2.1) There is a v_i - v_j path P in C', for some i, j, that includes some edge of some block or at least 4 bridges.

W.l.o.g. assume (i, j) = (1, 2). In this case we build S' as in Case 1. The cost analysis works almost identically as in Case 1. In this case C provides 1 credit only (rather than 5/3), but in both subcases this is enough. In particular, in the case P includes at least 4 bridges they provide $4 \cdot \frac{1}{4} = 1$ credits which makes up for the loss of credit of C.

(2.2.2) $v_i v_j$ is a bridge of C', for some i, j.

W.l.o.g. assume (i, j) = (1, 2). In this case we build S' like in Case 2. The analysis is identical.

(2.2.3) None of the above cases.

This case is illustrated in Figure 12. Let $P_{v_iv_j}$ be the v_i - v_j path in C'. Observe that such paths consist of bridges only, and have length 2 or 3. W.l.o.g. assume $|E(P_{v_1v_2})| \ge |E(P_{v_1v_3})|$, $|E(P_{v_2v_3})|$. Since $2 \le |E(P_{v_1v_2})| \le 3$, v_3 cannot be an internal vertex of $P_{v_1v_2}$: indeed otherwise the path from v_3 to at least one of v_1 or v_2 would have length 1, a contradiction. However since $P_{v_1v_2}$ consists only of bridges and $|E(P_{v_1v_2})| \ge |E(P_{v_1v_3})|$, $|E(P_{v_2v_3})|$, at least one internal node w of $P_{v_1v_2}$ has degree at least 3 in C'. Note w is adjacent to v_1 or v_2 in C': assume w.l.o.g. $v_1w \in E(C')$. Set $S' := S \cup \{u_1v_1, u_2v_2\} \setminus \{u_1u_2, v_1w\}$. The nodes of C and C' belong to a single connected component C'' in S'. In C'' the bridges and blocks of C' remain the same, except for the removed bridge v_1w . The edges of the path $P = v_1u_1u_3u_2v_2$ are bridges of C''. Altogether

$$cost(S) - cost(S') \ge cr(C) + cr(v_1w) + cr(C') - cr(C'') - \sum_{e \in E(P)} cr(e) = 1 + \frac{1}{4} - 4 \cdot \frac{1}{4} > 0.$$



Figure 12. Illustration of Case 3 of Lemma 3.6. *S'* is obtained from *S* by adding the blue edges and removing the red ones.

In each case it is easy to check that *S*' is a 2-edge-cover and the number of components of *S*' is strictly less than the number of components of *S*. Furthermore, *S*' is canonical since each newly created block has at least 5 nodes and each newly created connected component has at least 6 edges (hence it is large).

Lemma 2.17 follows by repeated applications of Lemma 3.2 and Lemma 3.6.

3.2 Removing complex components

In this section we prove Lemma 2.18. Recall that initially we are given a canonical 2-edge-cover *S* where the only small components are pendant 4-cycles: we will maintain this invariant.

DEFINITION 3.7. We say that *P* is an *extending path* of a complex component *C*, if it is a path in $E(G) \setminus E(C)$ between two nodes of *C* such that $P = \{e_0\} \cup P_1 \cup \{e_1\} \cup P_2 \cup \{e_2\} \cdots \cup P_k \cup \{e_k\}$, $k \ge 0$, where P_1, \ldots, P_k are paths (possibly of length zero) in distinct components C_1, \ldots, C_k , resp., of $S \setminus E(C)$, and e_0, \ldots, e_k are edges in $E(G) \setminus S$.

Since C_1, \ldots, C_k are all distinct, and the only small components of *S* are pendant 4-cycles, either $P = \{e_0\} \cup P_1 \cup \{e_1\}$, with C_1 being a pendant 4-cycle, or C_1, \ldots, C_k are all large components. In the latter case, we say that *P* is a *clean* extending path. Notice that a clean extending path might consist of a single edge.

Consider what happens to the cost of *S* when we add the edges of a clean extending path $P_{uv} = \{e_0\} \cup P_1 \cup \{e_1\} \cup P_2 \cup \{e_2\} \cdots \cup P_k \cup \{e_k\}$ between nodes *u* and *v* of some complex component *C* of *S*. By doing this, the edges of P_{uv} and of every path in *C* from *u* to *v* become part of a block *B*. Therefore this operation cannot create any new bridge. The cost increases by k + 1 due to the extra edges of P_{uv} . The blocks of every C_i retain their credit, and we collect 1 credit from every C_i . Hence we earn at least *k* credits from the components along P_{uv} . Altogether, the cost increases by at most 1 based on the above arguments. We call such cost increase, the

increase of the cost due to P_{uv} , and denote it by $cost(P_{uv}) \leq 1$. We remark that in the following we sometimes add $\ell \geq 2$ clean extending paths simultaneously. In that case we will guarantee that they do not share any component C_i (we say that they are *component disjoint*): this way we can guarantee that the overall increase of the cost due to such paths is the sum of their individual cost increases, hence at most ℓ (otherwise we might overcount the credits gained from some component). In the following we might add several component disjoint extending paths and remove some edges from *C*. When doing this we will guarantee that the extending paths are still part of some block, despite removing edges of *C*: this way we maintain the invariant that we do not create new bridges and thus the above cost analysis holds.

We next show that we can extend the 3-matching Lemma 3.1 to work with extending paths. If *C* is a complex component of *S*, we define the graph G_C such that $V(G_C) = V(C)$, and for $u, v \in V(G_C)$, $uv \in E(G_C)$ iff $uv \in E(C)$ or there is an extending path from *u* to *v*.

LEMMA 3.8. Let C be a complex component of S, and (V_1, V_2) be a partition of the nodes of C such that $4 \le |V_1| \le |V_2|$. Then there is a matching of size 3 in G_C between V_1 and V_2 .

PROOF. We claim G_C has no non-isolating cut. Assume to get a contradiction that there is a non-isolating cut $\{u, v\}$ in G_C splitting G_C into components $C_1, C_2, \ldots, C_k, k \ge 2$. Since G is structured, $\{u, v\}$ is not a non-isolating cut of G. Therefore, there are at least 2 components among C_1, C_2, \ldots, C_k such that there is a path in $G \setminus \{u, v\}$ between them. Moreover, we can assume such path to be fully outside C. Indeed, all edges of C are in G_C , so a path P between two components among C_1, C_2, \ldots, C_k must contain an edge not in C (otherwise it would also be a path in G_C , a contradiction). Thus, the subpath of P that is fully outside C is a path between two components among C_1, C_2, \ldots, C_k . W.l.o.g. assume there is a path P in $G \setminus \{u, v\}$ between nodes $v_1 \in V(C_1)$ and $v_2 \in V(C_2)$ not using any edge of C. But then there exists an extending path between v_1 and v_2 : this implies that there exists an edge in $G_C \setminus \{u, v\}$ from v_1 to v_2 , a contradiction. The claim follows.

Now assume $|V_1|, |V_2| \ge 4$. Then if there is no matching of size 3 in G_C between V_1 and V_2 , using König-Egeváry Theorem, there exists a vertex cover V' of the bipartite graph induced by (V_1, V_2) in G_C of size at most 2. Notice that there is no edge between $V_1 \setminus V'$ and $V_2 \setminus V'$, where the latter sets have size at least 2. If V' is of size 2, then it is a non-isolating cut of G_C , a contradiction. If instead $V' = \{v'\}$, then v' is a cut vertex in G_C (hence in G), a contradiction.

For the sake of brevity, when given a complex component *C* of *S* and a subgraph *B* of *C*, we will usually say that we apply Lemma 3.8 to *B* instead of to $(V(B), V(C) \setminus V(B))$. Also, because *S* is canonical, every leaf-block of *C* has at least 5 nodes, so we can apply Lemma 3.8 to any partition V_1 , V_2 of V(C) if V_1 and V_2 both contain the nodes of some leaf-block.

The most complicated part of proving Lemma 2.18 is removing complex components without creating new small components. We do this in Lemma 3.9 whose proof is postponed.

LEMMA 3.9. Let *S* be a canonical 2-edge-cover of a structured graph *G* whose small components are pendant 4-cycles and that has at least one complex component. In polynomial time one can find a canonical 2-edge-cover *S'* of *G*, whose small components are pendant 4-cycles, with no more connected components than *S*, with fewer complex components than *S*, and such that $cost(S') \le cost(S)$.

After this, the only remaining components are large 2VC components and pendant 4-cycles. It is then quite simple to remove pendant 4-cycles and thus obtain a solution satisfying the conditions of Lemma 2.18. We show this first in the following simple lemma. Then, Lemma 2.18 follows by chaining Lemmas 3.9 and 3.10.

LEMMA 3.10. Let *S* be a canonical 2-edge-cover such that the only connected components of *S* are large 2VC components and pendant 4-cycles. Then in polynomial time one can find a 2-edge-cover *S'* such that the only components of *S'* are large 2VC components and $cost(S') \le cost(S)$.

PROOF. Let C_1 be a 4-cycle of S adjacent only to one connected component C_2 of S that is large and 2VC. Let B be the only block of C_2 . By applying the 3-matching Lemma 3.1 to C_1 we can find a matching $\{a_1a_2, b_1b_2\}$, with $a_1b_1 \in E(C_1)$ and $a_2, b_2 \in V(C_2)$. Set $S' := S \cup \{a_1a_2, b_1b_2\} \setminus \{a_1b_1\}$. In S' the nodes of C_1 and C_2 belong to a single large component C_3 with a single block B'. One has

$$cost(S) - cost(S') = cr(C_1) + cr(C_2) + cr(B) - cr(C_3) - cr(B') - 1 = \frac{4}{3} + 1 + 1 - 1 - 1 - 1 - 1 > 0.$$

By iterating the above construction we obtain the claim.

Notation in the figures of Lemma 3.9. In the coming figures, gray regions represent blocks or 4-cycles, blue edges are added to *S* and red edges are being removed from *S*. Blue curved line represent clean extending paths that are added to *S*. Edges in a complex component that become part of a new block are shown in green. The dashed edges represent other edges of *G* not in *S*.

PROOF OF LEMMA 3.9. Let *C* be any complex component of *S*. We will show how to modify *S* into a canonical 2-edge-cover *S'* without creating new connected components and in a way that V(C) is contained in a connected component *C'* of *S'*, and either *S'* has fewer connected components than *S* or *C'* has fewer bridges or fewer blocks than *C*. We then repeat this operation on *C'* until it becomes a (large) 2VC component.

For every $a, b \in C$ let P_{ab}^{C} be any path in C between them. We consider the following cases, assuming at each case that the previous ones do not hold.

(1) For some leaf-block *B*, there is a non-clean extending path P_{xy} from $x \in V(B) \setminus \{u\}$ to $y \in V(C) \setminus V(B)$, where *u* is the only cut vertex of *B*.

This case is illustrated in Figure 13. Let C' be the 4-cycle corresponding to P_{xy} and let $xa, a \in$



Figure 13. Lemma 3.9 Case 1.

V(C'), be the first edge of P_{xy} . Apply the 3-matching Lemma 3.1 to C' to get a matching $\{v_1w_1, v_2w_2, v_3w_3\}$, with $w_i \in C$, $v_i \in C'$ for all i. W.l.o.g. we can assume $w_1 = x$: indeed if $w_1 \neq x$, we can add ax to the matching and remove aw_i if any. Notice that at least one of v_2 or v_3 is adjacent to v_1 , say $v_1v_2 \in E(C')$ w.l.o.g. Set $S' := S \cup \{v_1w_1, v_2w_2\} \setminus \{v_1v_2\}$. In S', the path $E(C') \cup \{v_1w_1, v_2w_2\} \setminus \{v_1v_2\}$ is merged with B (and potentially more edges of C) into a single block B'. Hence one has

$$cost(S) - cost(S') \ge cr(B) + cr(C') - cr(B') - 1 = 1 + 4/3 - 1 - 1 > 0.$$

We will use the next remark repeatedly in the rest of the cases.

REMARK 3.11. Let *B* be any leaf-block with cut vertex *u*, and assume that Case 1 does not hold. Apply Lemma 3.8 to *B*. There are two extending paths with distinct endpoints from $v_1, v_2 \in V(B) \setminus \{u\}$ to $w_1, w_2 \in V(C) \setminus V(B)$. Since Case 1 does not hold, these paths are clean. Given $x \in V(C) \setminus V(B)$ at least one of those paths goes from *a* to *b*, where $a \in V(B) \setminus \{u\}$, $b \in V(C) \setminus (V(B) \cup \{x\})$.

(2) For some block *B*, there is a clean extending path P_{xy} from $x \in V(B)$ to $y \in V(C) \setminus V(B)$ such that there is a path P_{xy}^C containing an edge of *B* and either an edge of another block *B'* or at least 4 bridges.

This case is illustrated in Figure 14. Set $S' := S \cup E(P_{xy})$. P_{xy} , B and all edges of P_{xy}^C are merged into a single block B'' of S'. If P_{xy}^C contains the edge of another block B' then B' is also part of B'' in S', and it brings 1 credit. If P_{xy}^C contains at least 4 bridges each of them brings 1/4 credits, so we collect 1 credit from the edges of P_{xy}^C as well. Altogether

$$\operatorname{cost}(S) - \operatorname{cost}(S') \ge \operatorname{cr}(B) + \operatorname{cr}(P_{xy}^{\mathcal{C}}) - \operatorname{cr}(B'') - \widetilde{\operatorname{cost}}(P_{xy}) \ge 1 + 1 - 1 - 1 = 0.$$

REMARK 3.12. Assuming that Cases 1 and 2 do not hold, every leaf-block *B* must have at least one bridge incident to them. Otherwise, let *u* be the cut vertex of *B*. By Remark 3.11, there is a clean extending path from a vertex $v \in V(B) \setminus \{u\}$ to some $w \in V(C) \setminus V(B)$. Since no bridge is



Figure 14. Lemma 3.9 Case 2.

incident to u, P_{wu}^{C} includes the edge of another block B', and thus P_{vw}^{C} includes edges of both B and B', which is excluded by Case 2.

Let C^* be the block-cutpoint graph (see Section 1.2) of C, and take a longest path P^* in the tree C^* . Note that the endpoints of this paths are two leaf-blocks. Let B be the block corresponding to one of those leaves. By Remark 3.12 and because P^* is a longest path, B must have exactly one bridge $u_0u_1, u_0 \in V(B)$, incident to it. P^* is the path $b_1c_1b_2c_2b_3c_3\ldots$, where b_1, b_2, \ldots are blocks or bridges of C, c_1, c_2, \ldots are cut vertices of C and b_1, c_1, b_2 correspond to B, u_0 and u_0u_1 , respectively. Consider the maximal sequence b_2, b_3, \ldots such that b_i is a bridge of C for all $i \ge 2$, and let $u_0u_1u_2u_3\ldots$ be the path of bridges corresponding to that sequence. For every $i \ge 0$, let $A(u_i)$ be the set of nodes (other than u_i) with paths in C to u_i that do not go through u_{i-1} or u_{i+1} . Observe that the sets $A(u_i)$ are disjoint and that $V(B) \setminus \{u_0\} \subseteq A(u_0)$. An example of how C and P^* might look like is shown in Figure 15.



Figure 15. A representation of *C* with respect to the path P^* . Recall that, because of Remark 3.12, every leaf-block must have a bridge incident to it.



Figure 16. Lemma 3.9 Case 3.

(3) There is clean extending path P_{vw} from $v \in V(B) \setminus \{u_0\}$ to $w \in A(u_1)$.

This case is illustrated in Figure 16. No path $P_{wu_0}^C$ can include the edge of a block distinct from B, because of Case 2. Thus $P_{wu_0}^C$ consists only of bridges. Also, since P^* is a longest path, $P_{wu_1}^C$ consists of a single bridge u_1w and $w \in V(B')$, where B' is a leaf-block of C distinct from B. Apply Remark 3.11 to B' to find a clean extending path P_{xy} from $x \in V(B') \setminus \{w\}$, to $y \in V(C) \setminus V(B')$. Let us first argue that the paths P_{vw} and P_{xy} are component disjoint. If that is not the case then there is a clean extending path P_{vx} from v to x, but since every P_{vx}^C includes at least an edge of B and an edge of B' this is excluded by Case 2.

Notice that every path $P_{yu_0}^C$ must not use u_1w . Otherwise, since P^* is a longest path, it must be that $y \in B''$, where B'' is another leaf-block with $w \in V(B'')$, and P_{xy}^C contains the edges of two distinct blocks, a contradiction by Case 2. Set $S' := S \cup E(P_{vw}) \cup E(P_{xy}) \setminus \{u_1w\}$, so that Band B' are merged into a single block B'' by the paths P_{vw} and $P_{xy} \cup P_{yu_0}^C$. One has

$$cost(S) - cost(S') \ge cr(B) + cr(B') + 1 - cr(B'') - cost(P_{vw}) - cost(P_{xy})$$

 $\ge 1 + 1 + 1 - 1 - 1 - 1 = 0.$

(4) There is a clean extending path P_{vw} from $v \in V(B) \setminus \{u_0\}$ to $w \in A(u_2)$.

By Case 2 it must be that every $P_{wu_0}^C$ contains no edge of a block and $|E(P_{wu_0}^C)| \le 3$. Thus there is a bridge u_2w in C and $P_{wu_0}^C = wu_2u_1u_0$.

(4.1) There is another bridge $ww', w' \neq u_2$.

This case is illustrated in Figure 17. Since P^* is a longest path, $w' \in V(B')$, where B' is a leafblock of C distinct from B. Apply Remark 3.11 to B' to find a clean extending path P_{xy} from $x \in V(B') \setminus \{w'\}$ to $y \in V(C) \setminus (V(B') \cup \{w\})$. Notice that P_{xy} and P_{vw} are component disjoint, otherwise there is a clean extending path P_{vx} from v to x, which is excluded by Case 2.

Let C_1 and C_2 be the connected components resulting from removing the bridge u_2w , with $V(B) \subset V(C_1)$. If $y \in V(C_2)$ then either $y \in V(B'')$, where B'' is another leaf-block with $w' \in V(B'')$, and P_{xy}^C contains the edges of two distinct blocks (a contradiction by Case 2), or



Figure 17. Lemma 3.9 Case 1.

we are in a case symmetric to Case 3 (with *B*' in place of *B*). So we can assume $y \in V(C_1)$ and therefore $w \notin V(P_{yu_0}^C)$. Set $S' := S \cup E(P_{vw}) \cup E(P_{xy})$, so that in *S*', *B* and *B*' are merged into a block *B*'' of *S*' through the paths $P_{vw} \cup \{ww'\}$ and $P_{xy} \cup P_{yu_0}^C$. Observe that the path $P_{wu_0}^C$ is also part of *B*'' in *S*'. One has

$$cost(S) - cost(S') \ge cr(B) + cr(B') + cr(ww') + cr(wu_2) + cr(u_2u_1) + cr(u_1u_0) - cr(B'') - \widetilde{cost}(P_{vw}) - \widetilde{cost}(P_{xy}) \ge 1 + 1 + 4 \cdot 1/4 - 1 - 1 - 1 = 0.$$

(4.2) There is no bridge $ww', w' \neq u_2$.

This case is illustrated in Figure 18. Using the fact that P^* is a longest path and Remark 3.12, it must be that $w \in V(B')$ for some leaf-block B' of C distinct from B. Apply Remark 3.11 to B' to find a clean extending path P_{xy} from $x \in V(B') \setminus \{w\}$ to $y \in V(C) \setminus V(B')$. As in the previous case, P_{xy} and P_{vw} are component disjoint, otherwise there is a clean extending path P_{vx} from v to x, which is excluded by Case 2.

If $wu_2 \in E(P_{yu_0}^C)$ for some path $P_{yu_0}^C$, it must be that $y \in V(B'')$, where B'' is another leaf-block of C with $w \in V(B'')$, a contradiction by Case 2. Set $S' := S \cup E(P_{vw}) \cup E(P_{xy}) \setminus \{u_2w\}$, so that B and B' are merged into a single block B'' of S' through the paths P_{vw} and $P_{xy} \cup P_{yu_0}^C$. Then we get

$$cost(S) - cost(S') \ge cr(B) + cr(B') + 1 - cr(B'') - cost(P_{vw}) - cost(P_{xy})$$

 $\ge 1 + 1 + 1 - 1 - 1 - 1 = 0.$

(5) There are two clean extending paths $P_{v_1u_2}$ and $P_{v_2u_3}$ from $v_1, v_2 \in V(B) \setminus \{u_0\}, v_1 \neq v_2$ to u_2 and u_3 .

Notice that $P_{v_1u_2}$ and $P_{v_2u_3}$ might not be component disjoint. Removing the bridge u_2u_3 splits C into 2 connected components C_1, C_2 , with $V(B) \subseteq V(C_1)$.



Figure 18. Lemma 3.9 Case 2.

(5.1) There is a non-clean extending path P_{ab} from $a \in V(C_1)$ to $b \in V(C_2)$.

This case is illustrated in Figure 19. Let C' be the 4-cycle corresponding to P_{ab} and let aa' and bb' be the first and last edges of P_{ab} . Apply the 3-matching Lemma 3.1 to C' to get a matching $\{x_1y_1, x_2y_2, x_3y_3\}$, with $x_i \in C$, $y_i \in C'$ for all i.

Let us prove that we can assume w.l.o.g. that $x_1 \in V(C_1)$, $x_2 \in V(C_2)$ and $y_1y_2 \in E(C')$. First notice that we can assume w.l.o.g. that neither $x_i \in V(C_1)$ for all $i \in \{1, 2, 3\}$ nor $x_i \in V(C_2)$ for all $i \in \{1, 2, 3\}$. Indeed, if $x_i \in V(C_1)$ for $i \in \{1, 2, 3\}$ add *bb'* to the matching and remove x_ib' if any. Symmetrically if $x_i \in V(C_2)$ for $i \in \{1, 2, 3\}$ add *aa'* to the matching and remove x_ia' if any. Now assume $x_1, x_3 \in V(C_1)$ and $x_2 \in V(C_2)$. Since *C'* is a 4-cycle, at least one of y_1, y_3 , say w.l.o.g. y_1 , is adjacent to y_2 in *C'*, so $x_1 \in V(C_1)$, $x_2 \in V(C_2)$ and $y_1y_2 \in E(C')$. The case where two of x_1, x_2, x_3 belong to $V(C_2)$ is symmetric. From now on we assume that $x_1 \in V(C_1)$, $x_2 \in V(C_2)$ and $y_1y_2 \in E(C')$.

Set $S' := S \cup E(P_{v_2u_3}) \cup \{x_1y_1, x_2y_2\} \setminus \{y_1y_2\}$. Notice that since $x_1 \in V(C_1), x_2 \in V(C_2)$, there are vertex disjoint paths $P_{x_1u_2}^C$ and $P_{x_2u_3}^C$. Adding $P_{v_2u_3}$ merges B and $P_{u_0u_3}^C = u_0u_1u_2u_3$ into a single block, and adding $E(C') \cup \{x_1y_1, x_2y_2\} \setminus \{y_1y_2\}$ merges that block and the paths $P_{x_1u_2}^C$, $P_{x_2u_3}^C$ into a new block B' of S'. One has

$$cost(S) - cost(S') \ge cr(B) + cr(C') + cr(u_0u_1) + cr(u_1u_2) + cr(u_2u_3)$$
$$- cr(B') - \widetilde{cost}(P_{v_2u_3}) - 1 \ge 1 + 4/3 + 3 \cdot 1/4 - 1 - 1 - 1 > 0.$$

(5.2) All extending paths between nodes of C_1 and C_2 are clean.

This case is illustrated in Figure 20. Apply Lemma 3.8 to $(V(C_1), V(C_2))$. By the hypothesis of this case, there must be at least one clean extending path P_{xy} from $x \in V(C_2) \setminus \{u_3\}$ to $y \in V(C_1) \setminus \{u_0\}$. Since $x \neq u_3$, $P_{xu_3}^C$ is not empty, and it contains at least one edge e. Thus, $|E(P_{xu_0}^C)| \ge 4$, so $y \notin A(u_0)$ by Case 2, and thus $y \in A(u_1) \cup A(u_2) \cup \{u_1, u_2\}$. Observe that the paths P_{xy} and $P_{v_1u_2}$ are component disjoint. Indeed, otherwise there is a clean extending path P_{v_1x} from v_1 to x, and there is a path $P_{v_1x}^C$ that includes an edge of B and at least 4 other edges



not in *B* (since $|E(P_{xu_0}^C)| \ge 4$); this is excluded by Case 2. By a similar argument P_{xy} and $P_{v_2u_3}$ are also component disjoint.

If $y \in A(u_1) \cup \{u_1\}$ set $S' := S \cup E(P_{v_1u_2}) \cup E(P_{xy}) \setminus \{u_1u_2\}$. Notice that u_1u_2 is neither in $P_{u_1y}^C$ nor in $P_{xu_3}^C$. The path $\{u_0u_1\} \cup P_{u_1y}^C \cup P_{xy} \cup P_{xu_3}^C \cup \{u_2u_3\} \cup P_{v_1u_2}$ is merged with *B* into a single block *B'* of *S'*. If *e* is the edge of a block then that block is also merged into *B'*, bringing 1 credit, and if it is a bridge it brings 1/4 credits, so we get at least 1/4 credits from the edges of $P_{xu_3}^C$. One has

$$cost(S) - cost(S') \ge cr(B) + cr(u_0u_1) + cr(u_1u_2) + cr(u_2u_3) + 1/4 + 1$$
$$- cr(B') - \widetilde{cost}(P_{v_1u_2}) - \widetilde{cost}(P_{xy}) \ge 1 + 4 \cdot 1/4 + 1 - 1 - 1 - 1 = 0.$$

If $y \in A(u_2) \cup \{u_2\}$ set $S' := S \cup E(P_{v_2u_3}) \cup E(P_{xy}) \setminus \{u_2u_3\}$. Notice that u_2u_3 is neither in $P_{u_2y}^C$ nor in $P_{xu_3}^C$. The path $\{u_0u_1\} \cup \{u_1u_2\} \cup P_{u_2y}^C \cup P_{xy} \cup P_{xu_3}^C \cup P_{v_2u_3}$ is merged with *B* into a single block *B'* of *S'*. As before, if *e* is the edge of a block then that block is also merged into *B'*, bringing 1 credit, and if it is a bridge it brings 1/4 credits, so we get at least 1/4 credits from the edges of $P_{xu_3}^C$. One has

$$cost(S) - cost(S') \ge cr(B) + cr(u_0u_1) + cr(u_1u_2) + cr(u_2u_3) + 1/4 + 1$$
$$- cr(B') - \widetilde{cost}(P_{v_2u_3}) - \widetilde{cost}(P_{xy}) \ge 1 + 4 \cdot 1/4 + 1 - 1 - 1 - 1 = 0$$

REMARK 3.13. Assume that all previous cases do not hold. Then, if there is a clean extending path P_{vw} from $v \in V(B) \setminus \{u_0\}$ to $w \in V(C) \setminus V(B)$ one has $w \in \{u_1, u_2, u_3\}$. To see this, notice that by Case 2 and since the path from every $u \in A(u_0)$ to u_0 contains the edge of a block, $w \notin A(u_0)$. By Cases 3 and 4 $w \notin A(u_1) \cup A(u_2)$, and by Case 2 $w \in A(u_0) \cup A(u_1) \cup A(u_2) \cup \{u_1, u_2, u_3\}$, because otherwise $|E(P_{wu_0}^{C})| \ge 4$.



Figure 20. Lemma 3.9 Case 2. We show the two possibilities, $y \in A(u_1) \cup \{u_1\}$ and $y \in A(u_2) \cup \{u_2\}$.

(6) None of the previous cases hold.

Many subcases of this case are analogous to previous cases; however, we include them all here for the sake of completeness. Apply Lemma 3.8 to *B* to find a matching $\{e_1, e_2, e_3\}$ in G_C . Since *B* is a leaf-block, we can assume w.l.o.g. that e_1, e_2 correspond to extending paths with distinct endpoints from $V(B) \setminus \{u_0\}$ to $V(C) \setminus V(B)$. Since Case 1 does not hold, those paths are clean. By Remark 3.13 and the fact that Case 5 does not hold, at least one of those paths has an endpoint in u_1 and the other in either u_2 or u_3 . This implies that e_1, e_2 correspond to clean extending paths $P_{v_1u_1}, P_{v_2w_2}$ with distinct endpoints from $v_1, v_2 \in V(B) \setminus \{u_0\}$ to u_1 and $w_2 \in \{u_2, u_3\}$, resp.

(6.1) There is a leaf-block B' with $V(B') \subset A(u_0)$ distinct from B.

This case is illustrated in Figure 21. Apply Remark 3.11 to B' to find a clean extending path P_{xy} from $x \in V(B') \setminus \{u_0\}$, to $y \in V(C) \setminus V(B')$. Note that by Case 2 we have $y \notin A(u_0)$ since otherwise $P_{yu_0}^C$ would include the edge of a block distinct from B'. Set $S' := S \cup E(P_{v_1u_1}) \cup E(P_{xy}) \setminus \{u_0u_1\}$, so that B and B' are merged into a single block B'' of S' through the paths $P_{v_1u_1} \cup P_{yu_1}^C$ and P_{xy} . Notice that by Case 2, $P_{v_1u_1}$ and P_{xy} are component disjoint. One has

$$cost(S) - cost(S') \ge cr(B) + cr(B') + 1 - cr(B'') - \widetilde{cost}(P_{v_1u_1}) - \widetilde{cost}(P_{xy})$$

 $\ge 1 + 1 + 1 - 1 - 1 - 1 = 0.$

(6.2) There is a non-clean extending path P_{u_0w} from u_0 to $w \in V(\mathcal{C}) \setminus V(\mathcal{B})$.

This case is illustrated in Figure 22. Let C' be the pendant 4-cycle corresponding to P_{u_0w} . Apply the 3-matching Lemma 3.1 to C' to get a matching $\{x_1y_1, x_2y_2, x_3y_3\}$ with $x_i \in C$, $y_i \in C'$ for all i. W.l.o.g. we can assume $x_1 = u_0$ and $y_1y_2 \in E(C')$. If $x_1 \neq u_0$ we can add the first edge of P_{u_0w} to



Figure 21. Lemma 3.9 Case 1.



the matching and remove any edge sharing an endpoint with it. Since one of y_2 or y_3 must be adjacent to y_1 we can also assume $y_1y_2 \in E(C')$. By exclusion of Case 1, every path in *C* from u_1 to x_2 does not include the edge u_0u_1 . Set $S' := S \cup E(P_{v_1u_1}) \cup \{u_0y_1, x_2y_2\} \setminus \{u_0u_1, y_1y_2\}$. Observe that $P_{v_1u_1}, E(C') \cup \{u_0y_1, x_2y_2\} \setminus \{y_1y_2\}$, and $P_{x_2u_1}^C$ form a path from v_1 to u_0 such that its inner vertices are not in *B*, and thus in *S'* they are merged with *B* into a single block *B'* of *S'*. One has

$$cost(S) - cost(S') \ge cr(B) + cr(C') - cr(B') - cost(P_{v_1u_1}) \ge 1 + 4/3 - 1 - 1 > 0.$$

REMARK 3.14. For every clean extending path P_{u_0w} from u_0 to $w \in V(C) \setminus (V(B) \cup \{u_1, w_2\})$, P_{u_0w} and $P_{v_1u_1}$ are component disjoint. Indeed, otherwise there exists a clean extending path P_{v_1w} from and v_1 to w, and by Remark 3.13, $w \in \{u_2, u_3\}$. This, together with the path $P_{v_2w_2}$, constitute a contradiction to the fact that Case 5 does not hold.

(6.3) There is a clean extending path P_{u_0w} from u_0 to $w \in V(C) \setminus (V(B) \cup \{u_1, w_2\})$ such that there is a path $P_{u_0w}^C$ containing the edge of another block B' or at least 4 bridges.

This case is illustrated in Figure 23. By Remark 3.14, $P_{v_1u_1}$ and P_{u_0w} are component disjoint. Set $S' := S \cup E(P_{v_1u_1}) \cup E(P_{u_0w}) \setminus \{u_0u_1\}$. Notice that $P_{u_1w}^C$ does not include the edge u_0u_1 , since by Case 1, $A(u_0) = V(B) \setminus \{u_0\}$. The paths $P_{u_0w} \cup P_{u_1w}^C$ and $P_{v_1u_1}$ are merged with *B* into a single block *B*" of *S*'. All edges of $P_{u_0w}^C$ (except u_0u_1) are also included in *B*". If one of those edges is the edge of another block it gets merged as well in *B*", and if not we get the credit from 4 bridges.



Figure 23. Lemma 3.9 Case 3.

In both cases we get at least 1 credit. One has

$$cost(S) - cost(S') \ge 1 + 1 - \widetilde{cost}(P_{v_1u_1}) - \widetilde{cost}(P_{u_0w}) \ge 1 + 1 - 1 - 1 = 0.$$

(6.4) There is a clean extending path P_{u_0w} from u_0 to $w \in A(u_1)$.

This case is illustrated in Figure 24. By Case 3 and the fact that $u_1, w_2 \notin A(u_1)$, no path $P_{u_0w}^C$ contains the edge of another block B'. Thus, $P_{u_0w}^C$ consists only of bridges. Also, since P^* is a longest path, $P_{wu_1}^C$ consists of a single bridge u_1w and $w \in V(B')$, where B' is a leaf-block of C distinct from B. Apply Remark 3.11 to find a clean extending path P_{xy} from $x \in V(B') \setminus \{w\}$ to $y \in V(C) \setminus V(B')$.

Let us first argue that the paths P_{u_0w} , $P_{v_1u_1}$ and P_{xy} are pair-wise component disjoint. By Remark 3.14, P_{u_0w} and $P_{v_1u_1}$ are component disjoint. If $P_{v_1u_1}$ and P_{xy} are not component disjoint, then there is a clean extending path P_{v_1x} from $v_1 \in V(B) \setminus \{u_0\}$ to x, a contradiction by Case 2. If P_{u_0w} and P_{xy} are not component disjoint then there is a clean extending path P_{u_0x} from u_0 to x. Since every $P_{u_0x}^C$ includes at least an edge of B' this is excluded by Case 3.

Notice that every path $P_{yu_1}^C$ must not use u_1w . Otherwise, since P^* is a longest path, it must be that $y \in B''$, where B'' is another leaf-block with $w \in V(B'')$, and P_{xy}^C contains the edges of two distinct blocks, a contradiction by Case 2. Also, every path $P_{yu_1}^C$ does not use u_0u_1 , because by exclusion of Cases 1 and 3, $y \notin A(u_0) \cup \{u_0\}$. Set $S' := S \cup E(P_{v_1u_1}) \cup E(P_{u_0w}) \cup E(P_{xy}) \setminus \{u_0u_1, u_1w\}$, so that B and B' are merged into a single block B'' through the paths P_{u_0w} and $P_{xy} \cup P_{yu_1}^C \cup P_{u_1v_1}$. One has

$$cost(S) - cost(S') \ge cr(B) + cr(B') + 2 - cr(B'') - \widetilde{cost}(P_{v_1u_1}) - \widetilde{cost}(P_{u_0w}) - \widetilde{cost}(P_{xy})$$
$$\ge 1 + 1 + 2 - 1 - 1 - 1 - 1 = 0.$$

(6.5) There is clean extending path P_{u_0w} from u_0 to $w \in A(u_2)$.

By Case 3 and the fact that $u_1, w_2 \notin A(u_2)$ it must be that every $P_{wu_0}^C$ contains no edge of a block and $|E(P_{wu_0}^C)| \leq 3$. Thus there is a bridge u_2w in C and $P_{wu_0}^C = wu_2u_1u_0$.



Figure 24. Lemma 3.9 Case 4.

(6.5.1) There is another bridge ww', $w' \neq u_2$.

This case is illustrated in Figure 25. Since P^* is a longest path, $w' \in V(B')$, where B' is a leafblock of C distinct from B. Apply Remark 3.11 to B' to find a clean extending path P_{xy} from $x \in V(B') \setminus \{w'\}$ to $y \in V(C) \setminus (V(B') \cup \{w\})$. Notice that P_{xy} and $P_{v_1u_1}$ are component disjoint, otherwise there is a clean extending path P_{v_1x} from v_1 to x, which is excluded by Case 2. Also, P_{u_0w} and P_{xy} are also component disjoint, otherwise there is a clean extending path P_{u_0x} from u_0 to x, which is excluded by Case 3. Thus, by Remark 3.14, P_{xy} , $P_{v_1u_1}$ and P_{u_0w} are pair-wise component disjoint.

Let C_1 and C_2 be the connected components resulting from removing the bridge u_2w , with $V(B) \subset V(C_1)$. If $y \in V(C_2)$ then either $y \in V(B'')$, where B'' is another leaf-block with $w' \in V(B'')$, and P_{xy}^C contains the edges of two distinct blocks (a contradiction by Case 2), or we are in a case symmetric to Case 3 (with B' in place of B). So we can assume $y \in V(C_1)$ and therefore $w \notin V(P_{yu_1}^C)$. Also, every path $P_{yu_1}^C$ does not use u_0u_1 , because by exclusion of Cases 1 and 3, $y \notin A(u_0) \cup \{u_0\}$. Set $S' := S \cup E(P_{u_0w}) \cup E(P_{v_1u_1}) \cup E(P_{xy}) \setminus \{u_0u_1\}$, so that in S', B and B'are merged into a block B'' of S' through the paths $P_{u_0w} \cup \{ww'\}$ and $P_{xy} \cup P_{yu_1}^C \cup P_{v_1u_1}$. Observe that the path $P_{wu_1}^C$ is also part of B'' in S'. One has

$$cost(S) - cost(S') \ge cr(B) + cr(B') + cr(ww') + cr(wu_2) + cr(u_2u_1) + cr(u_1u_0) + 1$$
$$- cr(B'') - \widetilde{cost}(P_{u_0w}) - \widetilde{cost}(P_{xy}) - \widetilde{cost}(P_{v_1u_1})$$
$$\ge 1 + 1 + 4 \cdot 1/4 + 1 - 1 - 1 - 1 - 1 = 0.$$

(6.5.2) There is no bridge $ww', w' \neq u_2$.

This case is illustrated in Figure 26. Using the fact that P^* is a longest path and Remark 3.12, it must be that $w \in V(B')$ for some leaf-block B' of C distinct from B. Apply Remark 3.11 to B' to find a clean extending path P_{xy} from $x \in V(B') \setminus \{w\}$ to $y \in V(C) \setminus V(B')$. By the same arguments as in the previous case, $P_{v_1u_1}$, P_{u_0w} and P_{xy} are pair-wise component disjoint.



Figure 25. Lemma 3.9 Case 1.





If $wu_2 \in E(P_{yu_1}^C)$ for some path $P_{yu_1}^C$, it must be that $y \in V(B'')$, where B'' is another leaf-block of C with $w \in V(B'')$, a contradiction by Case 2. Thus, one has $wu_2 \notin P_{yu_1}^C$. Also, by exclusion of Cases 1 and 3, $u_0u_1 \notin P_{yu_1}^C$. Set $S' := S \cup E(P_{v_1u_1}) \cup E(P_{u_0w}) \cup E(P_{xy}) \setminus \{u_0u_1, u_2w\}$, so that B and B' are merged into a single block B'' of S' through the paths P_{u_0w} and $P_{xy} \cup P_{yu_1}^C \cup P_{v_1u_1}$. Then we get

$$\cot(S) - \cot(S') \ge \operatorname{cr}(B) + \operatorname{cr}(B') + 2 - \operatorname{cr}(B'') - \widetilde{\operatorname{cost}}(P_{v_1u_1}) - \widetilde{\operatorname{cost}}(P_{u_0w}) - \widetilde{\operatorname{cost}}(P_{xy})$$
$$\ge 1 + 1 + 2 - 1 - 1 - 1 - 1 = 0.$$

(6.6) None of the previous cases hold.

Let us first show that there must exist a clean extending path $P_{u_0w_1}$ from u_0 to $w_1 \in \{u_2, u_3\} \setminus \{w_2\}$. Recall that $\{e_1, e_2, e_3\}$ is a matching in G_C such that e_1 and e_2 correspond to $P_{v_1u_1}$ and $P_{v_2w_2}$, respectively. Recall also that $w_2 \in \{u_2, u_3\}$. Notice that e_3 must be incident to u_0 in B, otherwise it is incident to some $v_3 \in V(B) \setminus \{u_0, v_1, v_2\}$ in B, and thus it corresponds to some extending path $P_{v_3w_1}$ from v_3 to $w_1 \in V(C) \setminus (V(B) \cup \{u_1, w_2\})$. By exclusion of Case 1, $P_{v_3w_1}$ is clean, and by Remark 3.13, it must be that $w_1 \in \{u_1, u_2, u_3\}$. Thus, the paths $P_{v_2w_2}$, $P_{v_3w_1}$ imply a contradiction



Figure 27. Lemma 3.9 Case 1.

to the fact that Case 5 does not hold. Therefore, e_3 is incident to u_0 in B. Notice that, since e_1 is incident to u_1 , it must be that e_3 is not incident to u_1 . But then, since u_0u_1 is the only bridge of Cincident to V(B) and Case 1 does not hold, the only edge of C not in B incident to u_0 is u_0u_1 , and thus it must be that the edge e_3 corresponds to some extending path $P_{u_0w_1}$ from u_0 to some node $w_1 \in V(C) \setminus (V(B) \cup \{u_1, w_2\})$.

Now, since Case 2 does not hold, $P_{u_0w_1}$ is clean. Since Cases 1, 4 and 5 do not hold, $w_1 \in V(C) \setminus (A(u_0) \cup A(u_1) \cup A(u_2) \cup \{u_0, u_1\})$. If $w_1 \in V(C) \setminus (A(u_0) \cup A(u_1) \cup A(u_2) \cup \{u_0, u_1, u_2, u_3\})$ then $|E(P_{wu_0}^C)| \ge 4$, so that Case 3 holds, a contradiction. Thus $w_1 \in \{u_2, u_3\} \setminus \{w_2\}$.

We remark that $P_{u_0w_1}$ and $P_{v_2w_2}$ might not be component disjoint. Removing the bridge u_2u_3 splits *C* into 2 connected components C_1, C_2 , with $V(B) \subset V(C_1)$.

(6.6.1) There is a non-clean extending path P_{ab} from $a \in V(C_1)$ to $b \in V(C_2)$.

This case is illustrated in Figure 27. Let C' be the 4-cycle corresponding to P_{ab} and let aa' and bb' be the first and last edges of P_{ab} . Apply the 3-matching Lemma 3.1 to C' to get a matching $\{x_1y_1, x_2y_2, x_3y_3\}$, with $x_i \in C$, $y_i \in C'$ for all i. By the same arguments as in Case 1, we can assume w.l.o.g. that $x_1 \in V(C_1)$, $x_2 \in V(C_2)$ and $y_1y_2 \in E(C')$.

If $w_2 = u_3$, then the same construction and analysis as in Case 1 holds. Otherwise, one has $w_1 = u_3$. By Remark 3.14, the paths $P_{v_1u_1}$ and $P_{u_0u_3}$ are component disjoint. Set S' := $S \cup E(P_{v_1u_1}) \cup E(P_{u_0u_3}) \cup \{x_1y_1, x_2y_2\} \setminus \{u_0u_1, y_1y_2\}$. Notice that since $x_1 \in V(C_1), x_2 \in V(C_2)$, there are vertex disjoint paths $P_{x_1u_2}^C$ and $P_{x_2u_3}^C$. Moreover, by Case 1, none of those paths contains the edge u_0u_1 . Notice $P_{u_1u_3}^C = u_1u_2u_3$. Adding $P_{v_1u_1}$ and $P_{u_0u_3}$ and removing u_0u_1 merges *B* and $P_{v_1u_1} \cup P_{u_0u_3}^C$ into a single block, and adding $E(C') \cup \{x_1y_1, x_2y_2\} \setminus \{y_1y_2\}$ merges that block and the paths $P_{x_1u_2}^C$, $P_{x_2u_3}^C$ into a new block *B'* of *S'*. One has

$$cost(S) - cost(S') \ge cr(B) + cr(C') + cr(u_0u_1) + cr(u_1u_2) + cr(u_2u_3)$$
$$- cr(B') - \widetilde{cost}(P_{v_1u_1}) - \widetilde{cost}(P_{u_0u_3}) \ge 1 + 4/3 + 3 \cdot 1/4 - 1 - 1 - 1 > 0.$$

(6.6.2) All extending paths between nodes of C_1 and C_2 are clean.

This case is illustrated in Figure 28. Apply Lemma 3.8 to $(V(C_1), V(C_2))$. By the hypothesis of this case, there must be at least one clean extending path P_{xy} from $x \in V(C_2) \setminus \{u_3\}$ to $y \in V(C_1) \setminus \{u_0\}$. Since $x \neq u_3$, $P_{xu_3}^C$ is not empty, and it contains at least one edge e. Thus, $|E(P_{xu_0}^C)| \ge 4$, so $y \notin A(u_0)$ by Case 2, and thus $y \in A(u_1) \cup A(u_2) \cup \{u_1, u_2\}$. Observe that the paths $P_{v_1u_1}$ and P_{xy} are pair-wise component disjoint. Indeed, if $P_{v_1u_1}$ and P_{xy} are not component disjoint there is a clean extending path P_{v_1x} from v_1 to x, and there is a path $P_{v_1x}^C$ that includes an edge of B and at least 4 other edges not in B (since $|E(P_{xu_0}^C)| \ge 4$); this is excluded by Case 2. By a similar argument P_{xy} and $P_{v_2w_2}$ are also component disjoint. Also, the paths P_{u_0x} from u_0 to x, and there is a path $P_{u_0x}^C$ that includes an edge of B and at least 4 other wise there is a clean extending path P_{u_0x} from u_0 to x, and there is a path $P_{u_0x}^C$ that includes an edge of B and at least 4. Since $|E(P_{xu_0}^C)| \ge 4$; this is excluded by Case 3. Finally, $P_{v_1u_1}$ and $P_{u_0w_1}$ are also component disjoint by Remark 3.14.

Assume first $y \in A(u_1) \cup \{u_1\}$. If $w_2 = u_2$ then the same construction and analysis as in Case 2, with $P_{v_2w_2}$ in place of $P_{v_1u_2}$ holds. Otherwise, one has $w_1 = u_2$. Set $S' := S \cup E(P_{v_1u_1}) \cup E(P_{u_0u_2}) \cup E(P_{xy}) \setminus \{u_0u_1, u_1u_2\}$. Notice that the edges u_0u_1, u_1u_2 are not in $P_{xu_3}^C$. Also, the edges u_0u_1, u_1u_2 are not in $P_{u_1y}^C \to E(P_{u_1y_1}) \cup E(P_{u_1y_2}) \cup E(P_{u_1y_2}) \cup E(P_{u_1y_2})$ because $y \in A(u_1) \cup \{u_1\}$. The path $P_{v_1u_1} \cup P_{u_1y_2}^C \cup P_{xy_2} \cup P_{xu_3}^C \cup \{u_2u_3\} \cup P_{u_0u_2}$ is merged with B into a single block B' of S'. If e is the edge of a block then that block is also merged into B', bringing 1 credit, and if it is a bridge it brings 1/4 credits, so we get at least 1/4 credits from the edges of $P_{xu_3}^C$. One has

$$\cot(S) - \cot(S') \ge \operatorname{cr}(B) + \operatorname{cr}(u_0 u_1) + \operatorname{cr}(u_1 u_2) + \operatorname{cr}(u_2 u_3) + 1/4 + 2$$
$$-\operatorname{cr}(B') - \widetilde{\operatorname{cost}}(P_{u_1 v_1}) - \widetilde{\operatorname{cost}}(P_{u_0 u_2}) - \widetilde{\operatorname{cost}}(P_{xy})$$
$$\ge 1 + 4 \cdot 1/4 + 2 - 1 - 1 - 1 - 1 = 0.$$

Assume now that $y \in A(u_2) \cup \{u_2\}$. If $w_2 = u_3$ then the same construction and analysis as in Case 2, with $P_{v_2w_2}$ in place of $P_{v_2u_3}$ holds. Otherwise, one has $w_1 = u_3$. Set $S' := S \cup E(P_{v_1u_1}) \cup E(P_{u_0u_3}) \cup E(P_{xy}) \setminus \{u_0u_1, u_2u_3\}$. By similar arguments as above, the edges u_0u_1, u_2u_3 are neither in $P_{xu_3}^C$ nor in $P_{u_2y}^C$. The path $P_{v_1u_1} \cup \{u_1u_2\} \cup P_{u_2y}^C \cup P_{xy} \cup P_{xu_3}^C \cup P_{u_0u_3}$ is merged with *B* into a single block *B'* of *S'*. As before, if *e* is the edge of a block then that block is also merged into *B'*, bringing 1 credit, and if it is a bridge it brings 1/4 credits, so we get at least 1/4 credits from the edges of $P_{xu_3}^C$. One has

$$cost(S) - cost(S') \ge cr(B) + cr(u_0u_1) + cr(u_1u_2) + cr(u_2u_3) + 1/4 + 2$$
$$- cr(B') - \widetilde{cost}(P_{v_1u_1}) - \widetilde{cost}(P_{u_0u_3}) - \widetilde{cost}(P_{xy})$$
$$\ge 1 + 4 \cdot 1/4 + 2 - 1 - 1 - 1 - 1 = 0.$$

Notice that in each case the constructed *S*' is canonical. Indeed, we never create connected components with fewer than 6 edges, nor any leaf-block with fewer than 5 nodes. Furthermore,



Figure 28. Lemma 3.9 Case 2.

each 4-cycle which is adjacent to a unique other large component *C*' preserves this property (though *C*' might turn from 2VC to complex or vice versa). Finally, the number of complex components decreases since we iteratively apply the above construction to a complex component *C* until it has only one block and thus is no longer a complex component.

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